# WILL THE USE OF GEOGEBRA IN GEOMETRY BE FACILITATED BY PROGRAMMING? 

Ernest SCHEIBER ${ }^{1}$


#### Abstract

In GeoGebra, the development method based on programming for geometry is exemplified by solving some Apollonius problems. For each problem we review the method used to build a GeoGebra tool and we reproduce the code. Finally, we indicate findings to facilitate the use of this approach.


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## 1 Introduction

In the last 30 years geometry software was created with the aim of supporting learning geometry and of visualizing geometric realities. At https://en. wikipedia.org/wiki/List_of_interactive_geometry_software there is a list of such software. An user has the possibility to obtain geometric drawings / constructions, to verify some statements and to visualize some geometric locus. The paper page is replaced by the monitor screen and the ruler and compass are replaced by commands to trace straight lines and circles.

We shall refer to the software GeoGebra, [5], [3], currently in continuous development. GeoGebra is a free product and is available in the cloud to be used. Plus there is a version for some Android devices. Interactively, picking an action from a menu and the required arguments GeoGebra executes the command. If it is the case, GeoGebra draws the generated object.

The purpose of this note is to underline another way of usage, closer to the traditional programming. For GeoGebra three facilities allow this approach:

1. For any action that can be picked from a menu there is a command as a call of a subroutine. The family of these commands allow users to solve a large set of problems.

[^0]2. There is an Input line where it is possible to edit / copy a command.
3. Finally, the geometric construction may be transformed into a tool, a kind of subroutine.

The technique isn't new. It is the development mode for Geometry Constructions LA $_{E} X$ Converter (GCLC), [1].

In the next section we exemplify this method giving codes to solve some cases of Apollonius problem. In the last section we indicate findings to facilitate the use of this approach.

## 2 The Apollonius problem

The Apollonius problem is to find / draw circles tangent to three things. The things may be points $(P)$, (straight) lines $(L)$ and circles $(C)$. The required circles must be tangent to the given circles and / or lines and pass through given points. It yields 10 problems:

| No. | The problem | Abbr. |
| :---: | :--- | :--- |
| 1 | Circle passing through three points | PPP |
| 2 | Circle tangent to three lines | LLL |
| 3 | Circle passing through two points and tangent to a line | PPL |
| 4 | Circle passing through a point and tangent to two lines | PLL |
| 5 | Circle tangent to two lines and a circle | LLC |
| 6 | Circle passing through a point and tangent to a line and a circle | PLC |
| 7 | Circle tangent to a line and two circles | LCC |
| 8 | Circle passing through two points and tangent to a circle | PPC |
| 9 | Circle passing through a point and tangent to two circles | PCC |
| 10 | Circle tangent to three circles | CCC |

Here we present the solutions for the last three problems. These problems are correlated, as it is indicated in Fig. 1.


Fig. 1: Dependency graph

The same approach is found in [2], [4], but without providing codes for geometric software. For each problem, we review the method used to build a GeoGebra tool and finally we reproduce the result of using that tool.

We used GeoGebra 5 (GeoGebra classic). With given data the lines of a script must be copied in turn to the Input line and executed.

### 2.1 PPC



Fig. 2: Reasoning image for solving the PPC problem

Let $A$ and $B$ be two points and the circle $c=\mathcal{C}(C)$, Fig. 2. The circle passing through the points $A, B, C$ intersects $c$ in the points $E_{1}, E_{2}$. It is supposed that the lines $A B$ and $E_{1} E_{2}$ are not parallel, case that occurs when the point $C$ is on the perpendicular bisector of segment $A B$.

If $\mathcal{C}(\Omega)$ is a solution of the PPC problem, then the lines $A B, E_{1} E_{2}$ and the exterior tangents to the circle $c$ intersect in $I$, the radical center of $c, \mathcal{C}(\Omega)$ and $\mathcal{C}(A, B, C)$.

If $T$ is the intersection between an exterior tangent and $c$ then $\mathcal{C}(\Omega)$ is the circle passing through $A, B$ and $T$. The following script results

$$
\begin{array}{|l|l}
\hline \hline 1 & d=\operatorname{circle}(A, B, C) \\
2 & E=\operatorname{intersect}(c, d) \\
3 & I=\operatorname{intersect}\left(\operatorname{line}\left(E_{1}, E_{2}\right), \operatorname{line}(A, B)\right) \\
4 & t=\operatorname{tangent}(I, c) \\
5 & e=\operatorname{circle}\left(\operatorname{intersect}\left(t_{1}, c\right), A, B\right) \\
6 & g=\operatorname{circle}\left(\operatorname{intersect}\left(t_{2}, c\right), A, B\right) \\
\hline
\end{array}
$$

The results of the PPC tool are given in Fig. 3.


Fig. 3: Results of calling $\operatorname{PPC}(A, B, C, D)$

## $2.2 \quad \mathrm{PCC}$

We need an additional tool for the similarities centers of two circles. Two circles $\mathcal{C}\left(O_{1}, r_{1}\right), \mathcal{C}\left(O_{2}, r_{2}\right)$, not included one in other, have an exterior similarity center. If the circles do not intersect, then there exists an interior similarity center, too. In Fig. 4, the point $S_{e}$ is the exterior similarity center, while $S_{i}$ is the interior similarity center.


Fig. 4: The similarity centers

If $r_{1}>r_{2}$, then the following relations hold

$$
\left|S_{e} O_{2}\right|=\frac{r_{2}}{r_{1}-r_{2}}\left|O_{1} O_{2}\right|, \quad\left|S_{i} O_{2}\right|=\frac{r_{2}}{r_{1}+r_{2}}\left|O_{1} O_{2}\right| .
$$

Based on the above relations, the GeoGebra script to fix the similarity centers is

| 1 | $f=\operatorname{line}(A, C)$ |
| :--- | :--- |
| 2 | $r 1=\operatorname{radius}(c)$ |
| 3 | $r 2=\operatorname{radius}(d))$ |
| 4 | $r e=\min (r 1, r 2) / \operatorname{abs}(r 1-r 2)$ |
| 5 | $E=\operatorname{intersect}(f, \operatorname{circle}(i f(r 1>r 2, C, A), r e * \operatorname{segment}(A, C))))$ |
| 6 | $S e=\operatorname{if}\left(r 1>r 2, E_{2}, E_{1}\right)$ |
| 7 | $r i=r 2 /(r 1+r 2)$ |
| 8 | $F=\operatorname{intersect}(f, \operatorname{circle}(C, r i * \operatorname{segment}(A, C)))$ |
| 9 | $S i=F_{1}$ |

We remind some properties related to the similarity centers:

- If the line $i$ intersects the circles $c$ and $d$ in the points $N_{1}, N_{2}$ and respectively $M_{1}, M_{2}$, Fig. 4, then the triangles $\triangle S_{e} O_{1} N_{1}$ and $\triangle S_{e} O_{2} M_{2}$ are similar. As a consequence it results that $O_{1} N_{1} / / O_{2} M_{1}$. A similar result occurs in the case of interior similarity center.
- If a circle $\mathcal{C}(\Omega, \rho)$ is tangent to the circles $\mathcal{C}\left(O_{i}, r_{i}\right), i \in\{1,2\}$ with the tangent points $T_{1}, T_{2}$, Fig. 5 , then the points $T_{1}, T_{2}, S_{e}$ are colinear. This may be proved using the Menelaus's Theorem in $\triangle \Omega O_{1} O_{2}$.
- Computing the power of $S_{e}$ w.r. to the circle $\mathcal{C}(\Omega)$, Fig. 5 , we obtain

$$
\begin{gather*}
\wp\left(S_{e}\right)=\left|S_{e} T_{1}\right| \cdot\left|S_{e} T_{2}\right|=\left|S_{e} T_{2}\right| \cdot\left|S_{e} T_{2}^{\prime}\right| \cdot \frac{\left|S_{e} T_{1}\right|}{\left|S_{e} T_{2}^{\prime}\right|}= \\
=\wp e_{\left(O_{2}\right)}\left(S_{e}\right) \cdot \frac{\left|S_{e} T_{1}\right|}{\left|S_{e} T_{2}^{\prime}\right|}=\left(\left|S_{e} O_{2}\right|^{2}-r_{2}^{2}\right) \cdot \frac{r_{1}}{r_{2}}=\left|S_{e} O_{1}\right| \cdot\left|S_{e} O_{2}\right|-r_{1} r_{2} . \tag{1}
\end{gather*}
$$

There is another meaning of the above equality. If we consider the inversion with center $S_{e}$ mapping the circle $\mathcal{C}\left(O_{2}, r_{2}\right)$ onto $\mathcal{C}\left(O_{1}, r_{1}\right)$ then the power of inversion is

$$
\rho^{2}=\left|S_{e} T_{1}\right| \cdot\left|S_{e} T_{2}\right|=\left|S_{e} O_{1}\right| \cdot\left|S_{e} O_{2}\right|-r_{1} r_{2} .
$$

We turn to the PCC problem.

Point $A$ and circles $\mathcal{C}\left(O_{1}, r_{1}\right)$ and $\mathcal{C}\left(O_{2}, r_{2}\right)$ are given. Fig. 5. Let be $S_{e}$ the exterior similarity center and suppose that the circle $\mathcal{C}(\Omega)$ is a solution to the PCC problem. We denote by

- $T_{1}$ and $T_{2}$ the tangent points between $\mathcal{C}(\Omega)$ and the given circles.
- $B$ the second intersection between the line $A S_{e}$ and $\mathcal{C}(\Omega)$.


Fig. 5: Reasoning image for solving the PCC problem

The points $T_{1}, T_{2}, S_{e}$ are collinear, (see 2.2).
Computing the power of $S_{e}$ w.r. to the circle $\mathcal{C}(\Omega)$ we get from (1)

$$
\wp\left(S_{e}\right)=\left(\left|S_{e} O_{2}\right|^{2}-r_{2}^{2}\right) \cdot \frac{r_{1}}{r_{2}}
$$

and also

$$
\wp\left(S_{e}\right)=\left|S_{e} A\right| \cdot\left|S_{e} B\right| .
$$

From the above two equalities it results the position of the point $B$

$$
\left|S_{e} B\right|=\left(\left|S_{e} O_{2}\right|^{2}-r_{2}^{2}\right) \cdot \frac{r_{1}}{r_{2} \cdot\left|S_{e} A\right|}
$$

Of course two possible solutions for the point $B$ result. In this way the PCC problem is reduced to the PPC problem: construct the circles passing through the points $A, B$ and tangent to circle $\mathcal{C}\left(O_{1}, r_{1}\right)$.

Considering the interior similarity center other solutions of the PCC problem result.

The GeoGebra script is

| 1 | $S=\operatorname{simCenters}(B, C, D, E)$ |
| :---: | :--- |
| 2 | $r 1=\operatorname{radius}(c)$ |
| 3 | $r 2=\operatorname{radius}(d)$ |
| 4 | $s 1=\left(\operatorname{segment}\left(S_{1}, D\right)^{2}-r 2^{2}\right) * r 1 /\left(r 2 * \operatorname{segment}\left(S_{1}, A\right)\right)$ |
| 5 | $F_{1}=\operatorname{intersect}\left(\operatorname{ray}\left(S_{1}, A\right), \operatorname{circle}\left(S_{1}, s 1\right)\right)$ |
| 6 | $o 1=P P C\left(A, F_{1}, B, C\right)$ |
| 7 | $s 2=\left(\operatorname{segment}\left(S_{2}, D\right)^{2}-r 2^{2}\right) * r 1 /\left(r 2 * \operatorname{segment}\left(S_{2}, A\right)\right)$ |
| 8 | $A^{\prime}=\operatorname{reflect}\left(A, S_{2}\right)$ |
| 9 | $F_{2}=\operatorname{intersect}\left(\operatorname{ray}\left(S_{2}, A^{\prime}\right), \operatorname{circle}\left(S_{2}, s 2\right)\right)$ |
| 10 | $o 2=P P C\left(A, F_{2}, B, C\right)$ |

Calling the corresponding GeoGebra tool the results are given in Fig. 6.


Fig. 6: Results of calling $\operatorname{PCC}(A, B, C, D, E)$

### 2.3 CCC



Fig. 7: Reasoning image for solving the CCC problem

Three circles $\mathcal{C}\left(O_{i}, r_{i}\right), i \in\{1,2,3\}$ with $r_{1}>r_{2}>r_{3}$ are given. See Fig. 7. If $\mathcal{C}(\Omega, \rho)$ is a solution, then circle $\mathcal{C}\left(\Omega, \rho-r_{3}\right)$ passes through the point $O_{3}$ and are tangent to the circles $\mathcal{C}\left(O_{i}, r_{i}+r_{3}\right), i \in\{1,2\}$. This is called the Viète method. Thus the problem CCC is reduced to the problem PCC.

The solutions will be obtained solving four PCC problems, generate the circles passing through $O_{3}$ and tangent to circles $\mathcal{C}\left(O_{1}, r_{1} \pm r_{3}\right)$ and $\mathcal{C}\left(O_{2}, r_{2} \pm r_{3}\right)$, considering all combinations of + and - operations.

The corresponding GeoGebra script is

| 1 | $c 1=\operatorname{circle}(A, \operatorname{radius}(c)+\operatorname{radius}(e))$ |
| :---: | :--- |
| 2 | $d 1=\operatorname{circle}(C, \operatorname{radius}(d)+\operatorname{radius}(e))$ |
| 3 | $B 1=\operatorname{point}(c 1)$ |
| 4 | $D 1=\operatorname{point}(d 1))$ |
| 5 | $o 1=P C C(E, A, B 1, C, D 1)$ |
| 6 | $q 1=\operatorname{circle}\left(\operatorname{center}\left(o 1_{2}\right), \operatorname{radius}\left(o 1_{2}\right)-\operatorname{radius}(e)\right)$ |
| 7 | $c 2=\operatorname{circle}(A, \operatorname{radius}(c)-\operatorname{radius}(e))$ |
| 8 | $d 2=\operatorname{circle}(C, \operatorname{radius}(d)-\operatorname{radius}(e))$ |
| 9 | $B 2=\operatorname{point}(c 2)$ |
| 10 | $D 2=\operatorname{point}(d 2)$ |
| 10 | $o 2=P C C(E, A, B 2, C, D 2)$ |
| 11 | $q 2=\operatorname{circle}\left(\operatorname{center}\left(o 2_{1}\right)\right.$, radius $\left.\left(o 2_{1}\right)-\operatorname{radius}(e)\right)$ |
| 12 | $r 2=\operatorname{circle}\left(\operatorname{center}\left(o 2_{2}\right)\right.$, radius $\left.\left(o 2_{2}\right)+\operatorname{radius}(e)\right)$ |
| 13 | $o 3=P C C(E, A, B 1, C, D 2)$ |
| 14 | $q 3=\operatorname{circle}\left(\operatorname{center}\left(o 3_{3}\right)\right.$, radius $\left.\left(o 3_{3}\right)+\operatorname{radius}(e)\right)$ |
| 15 | $r 3=\operatorname{circle}\left(\operatorname{center}\left(o 3_{4}\right)\right.$, radius $\left.\left(o 3_{4}\right)-\operatorname{radius}(e)\right)$ |
| 16 | $o 4=P C C(E, A, B 2, C, D 1)$ |
| 17 | $q 4=\operatorname{circle}\left(\operatorname{center}\left(o 4_{3}\right)\right.$, radius $\left.\left(o 4_{3}\right)+\operatorname{radius}(e)\right)$ |
| 18 | $r 4=\operatorname{circle}\left(\operatorname{center}\left(o 4_{4}\right)\right.$, radius $\left.\left(o 4_{4}\right)-\operatorname{radius}(e)\right)$ |

The results of the CCC tool are given in Fig. 8.


Fig. 8: The results of $\operatorname{CCC}(A, B, C, D, E, F)$

## 3 Conclusions

Instead of using the mouse to pick command from menus we prefer to edit / copy commands in the Input line. That is a more programmable style of using GeoGebra, at least formally. It would be useful for GeoGebra to offer the following possibilities:

- To upload and process a command file.
- The Manage Tool does not allow the possibility to upload tools. If a construction needs two custom tools then we shall start with a file with that tools, created successively, that's an annoying procedure.
- To introduce functions to set properties of objects, i.e. hide an object or a label, the parameters of lines, colors, e.t.c.
- To allow polymorphism tools.
- To offer a public Java API to be used outside GeoGebra but accessing GeoGebra.


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[^0]:    ${ }^{1}$ Faculty of Mathematics and Computer Science, Transilvania University of Braşov, Romania, e-mail: scheiber@unitbv.ro

