

AN ANISOTROPIC GEOMETRICAL APPROACH FOR EXTENDED RELATIVISTIC DYNAMICS

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Abstract

In this paper we present the distinguished (d-) pseudo-Riemannian geometry (in the sense of nonlinear connection, Cartan canonical linear connection, together with its d-torsions) for a Lagrangian inspired by relativistic optics in non-uniform media.

2010 *Mathematics Subject Classification*: 53C60, 53C80, 83C10.

Key words: Minkowski metric, anisotropic optics, nonlinear connection, Cartan linear connection, d-torsions.

1 Introduction

In the geometrical optics [3], a central role is played by the Synge-Beil metric [1], [6] and [7]

$$g_{\alpha\beta}(x, y) = \varphi_{\alpha\beta}(x) + \gamma^2 y_\alpha y_\beta, \quad (1)$$

where $\gamma(x) \geq 0$ is a positive smooth function on the space-time M^4 , and $\varphi_{\alpha\beta}(x)$ is a pseudo-Riemannian metric on M^4 . One assumes that the four-dimensional manifold M^4 (which is connected and simply connected) is endowed with the local coordinates $(x^\alpha)_{\alpha=\overline{1,4}} = (x^1 = t, x^2, x^3, x^4)$; for simplicity we use the system of units where the light velocity is $c = 1$. Obviously, the following rule holds good: $y_\alpha = \varphi_{\alpha\mu} y^\mu$. Because the components of $\varphi_{\alpha\beta}(x)$ are dimensionless, the same are γy_α : $[\varphi_{\alpha\beta}(x)] = 1$, $[\gamma y_\alpha] = 1$.

In such a context, let us restrict our geometric-physical study to the Minkowski manifold $\mathcal{M}^4 = (\mathbb{R}^4, \eta_{ij})$ which has the local coordinates $(x) := (x^i)_{i=\overline{1,4}}$. It follows that the corresponding tangent bundle $T\mathbb{R}^4$ has the dimension equal to

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eight, and its local coordinates are³

$$(x, y) := (x^i, y^i)_{i=1,4} = \left(\underbrace{x^1, x^2, x^3, x^4}_{\text{space-time coordinates}}, \underbrace{y^1, y^2, y^3, y^4}_{\text{tangent vector}} \right).$$

Let us introduce a metric on $T\mathbb{R}^4$ inspired by optics in a non-uniform medium (see formula (1)):

$$\mathfrak{g}_{ij}(x, y) = \eta_{ij} + \gamma^2(x)y_i y_j, \quad (2)$$

where $\eta = (\eta_{ij}) = \text{diag}(-1, 1, 1, 1)$ is the Minkowski metric, and $y_i = \eta_{ir}y^r$. Usually, we have $\gamma^2(x) = n^2(x) - 1$, where $n = n(x)$ is the refractive index of the non-uniform medium (see [1], [6] and [7]). Using the metric (2), below we will examine the special case of a possible anisotropic relativistic dynamical model, which is governed by the Lagrangian (in this model one considers that the particle has the mass $m = 1$)

$$\begin{aligned} L(x, y) &= \frac{1}{2} \mathfrak{g}_{ij}(x, y) y^i y^j = \\ &= \frac{1}{2} [\eta_{ij} + \gamma^2(x) y_i y_j] y^i y^j = \\ &= \frac{1}{2} \eta_{ij} y^i y^j + \frac{\gamma^2}{2} \|y\|^4, \end{aligned} \quad (3)$$

where $\|y\|^2 = -(y^1)^2 + (y^2)^2 + (y^3)^2 + (y^4)^2 = \eta_{ij} y^i y^j$.

Remark 1. *Because the Minkowski metric η_{ij} is invariant with respect to the linear transformations of coordinates induced by the Lorentz group $O(3, 1)$, it immediately follows that the Lagrangian (3) has a global geometrical character with respect to these Lorentz transformations.*

Following as a pattern the geometrical ideas from Lagrangian geometry of tangent bundles [5] or jet bundles [2], in what follows we construct the pseudo-Riemann-Lagrange geometrical objects (the canonical nonlinear connection, the Cartan canonical linear connection, together with its d-torsions) produced by the Lagrangian (3).

2 Geometrical objects in the relativistic extended dynamics

The fundamental metrical distinguished tensor induced by the Lagrangian (3) is given by

$$g_{ij}(x, y) = \frac{1}{2} \frac{\partial^2 L}{\partial y^i \partial y^j} = \sigma(x, y) \eta_{ij} + 2\gamma^2(x) y_i y_j,$$

where $\sigma(x, y) = (1/2) + \gamma^2(x) \|y\|^2 > 0$.

³In this paper the Latin letters i, j, k, \dots run from 1 to 4. The Einstein convention of summation is adopted all over this work.

Remark 2. Because the quadratic form $q(\xi) = (y_i y_j) \xi^i \xi^j$ is degenerate and has the signature $(3, 1, 0)$, while the Minkovski metric $\eta(\xi) = \eta_{ij} \xi^i \xi^j$ is non-degenerate and has the signature $(0, 3, 1)$, we easily deduce that the quadratic form $g(\xi) = g_{ij}(x, y) \xi^i \xi^j$ has the constant signature $(0, 3, 1)$. It follows that it is invariant under Lorentz linear transformation of coordinates. Consequently, all the subsequent geometrical objects constructed in this paper will have the same form in any chart of coordinates induced by a linear transformation of coordinates produced by the Lorentz group $O(3, 1)$.

The inverse matrix $g^{-1} = (g^{jk})$ has the entries

$$g^{jk}(x, y) = \frac{1}{\sigma(x, y)} \eta^{jk} - \frac{2\gamma^2(x)}{\sigma(x, y) \cdot \tau(x, y)} y^j y^k,$$

where $\eta^{jk} = \eta_{jk}$ and $\tau(x, y) = (1/2) + 3\gamma^2(x) \|y\|^2 = \sigma(x, y) + 2\gamma^2(x) \|y\|^2$.

Proposition 1. For the anisotropic Lagrangian (3), the action

$$\mathbb{E}(x(t)) = \int_a^b L(x(t), y(t)) dt,$$

where $y = dx/dt$, produces on the tangent bundle $T\mathbb{R}^4$ the **canonical nonlinear connection** $N = (N_j^i)$, whose components are

$$\begin{aligned} N_j^i &= \frac{2\gamma}{\sigma} y^i y_j (\gamma_s y^s) + \frac{\gamma \|y\|^2}{\sigma} \left[\delta_j^i (\gamma_s y^s) + y^i \gamma_j - \gamma^i y_j - \frac{2\gamma^2}{\sigma} y^i y_j (\gamma_s y^s) - \right. \\ &\quad \left. - \frac{6\gamma^2}{\tau} y^i y_j (\gamma_s y^s) \right] + \\ &\quad + \frac{\gamma^3 \|y\|^4}{2\sigma} \left[\frac{1}{\sigma} \gamma^i y_j - \frac{3}{\tau_M} y^i \gamma_j - \frac{3}{\tau} \delta_j^i (\gamma_s y^s) + \frac{6\gamma^2}{\sigma \tau^2} (\tau + 3\sigma) y^i y_j (\gamma_s y^s) \right], \end{aligned} \quad (4)$$

where $\gamma_s = \partial\gamma/\partial x^s$ and $\gamma^i = \eta^{ir} \gamma_r$.

Proof. For the energy action functional \mathbb{E} , the associated Euler-Lagrange equations can be written in the equivalent form (see [5] and [2])

$$\frac{d^2 x^i}{dt^2} + 2G^i(x^k(t), y^k(t)) = 0, \quad \forall i = \overline{1, 4}, \quad (5)$$

where the local components

$$\begin{aligned} G^i &\stackrel{def}{=} \frac{g^{ir}}{4} \left[\frac{\partial^2 L}{\partial y^r \partial x^s} y^s - \frac{\partial L}{\partial x^r} \right] = \\ &= \frac{\gamma}{\sigma} \|y\|^2 y^i (\gamma_s y^s) - \frac{\gamma}{4\sigma} \|y\|^4 \gamma^i - \frac{3\gamma^3}{2\sigma\tau} \|y\|^4 y^i (\gamma_s y^s) \end{aligned}$$

represent, from a geometrical point of view, a *semispray* on the tangent vector bundle $T\mathbb{R}^4$. The *canonical nonlinear connection* associated to this semispray has the components (see [5]) $N_j^i \stackrel{def}{=} \frac{\partial G^i}{\partial y^j}$.

In conclusion, by direct computations, we find the expression (4). \square

Remark 3. In a uniform medium with the constant refractive index $n(x) = n \in [1, \infty)$, we have $\gamma_s = 0$. Consequently, in this case we obtain $G^i = 0$ and $N_j^i = 0$.

The nonlinear connection (4) produces the dual adapted bases of d-vector fields

$$\left\{ \frac{\delta}{\delta x^i} = \frac{\partial}{\partial x^i} - N_i^r \frac{\partial}{\partial y^r} ; \frac{\partial}{\partial y^i} \right\} \subset \mathcal{X}(T\mathbb{R}^4) \quad (6)$$

and d-covector fields

$$\{ dx^i ; \delta y^i = dy^i + N_r^i dx^r \} \subset \mathcal{X}^*(T\mathbb{R}^4). \quad (7)$$

The naturalness of the geometrical adapted bases (6) and (7) is coming from the fact that, via a transformation of coordinates, their elements transform as tensors on \mathbb{R}^4 . Therefore, the description of all subsequent geometrical objects on the tangent space $T\mathbb{R}^4$ (e.g., the Cartan canonical linear connection and its torsion) will be done in local adapted components.

For instance, using the notations $N_{ij} := N_i^r \eta_{rj}$, $N_{i0} := N_{ir} y^r$, $N_{0j} := N_{rj} y^r$, $N_{00} := N_{ij} y^i y^j$, by direct local computations, we obtain the following geometrical result:

Proposition 2. The Cartan canonical N -linear connection produced by the anisotropic Lagrangian (3) has the adapted local components $C\Gamma(N) = (L_{jk}^i, C_{jk}^i)$, where

$$\begin{aligned} L_{jk}^i &= -\frac{\gamma}{\sigma} \left[\gamma \left(\delta_j^i N_{k0} + \delta_k^i N_{j0} - \eta^{ir} \eta_{jk} N_{r0} \right) + \|y\|^2 \left(\eta_{jk} \gamma^i - \delta_j^i \gamma_k - \delta_k^i \gamma_j \right) + \right. \\ &\quad \left. + \gamma \left\{ (N_{jk} + N_{kj}) y^i + (N_k^i - \eta^{ir} N_{rk}) y_j + (N_j^i - \eta^{ir} N_{rj}) y_k \right\} + \right. \\ &\quad \left. + 2 \left(\gamma^i y_j y_k - y^i y_j \gamma_k - y^i y_k \gamma_j \right) \right] + \frac{2\gamma^3 y^i}{\sigma\tau} \left[\gamma (y_j N_{k0} + y_k N_{j0} - \eta_{jk} N_{00}) + \right. \\ &\quad \left. + \|y\|^2 (\delta_{jk} \gamma_r y^r - y_j \gamma_k - y_k \gamma_j) + 2 (y_j y_k \gamma_r y^r - y_j \gamma_k \|y\|^2 - y_k \gamma_j \|y\|^2) + \right. \\ &\quad \left. + \gamma \left\{ (N_{jk} + N_{kj}) \|y\|^2 + (N_{k0} - N_{0k}) y_j + (N_{j0} - N_{0j}) y_k \right\} \right], \end{aligned} \quad (8)$$

$$C_{jk}^i = \frac{\gamma^2}{\sigma} (y^i \eta_{jk} + \delta_j^i y_k + \delta_k^i y_j) - \frac{2\gamma^4}{\sigma\tau} (\|y\|^2 \eta_{jk} + 2y_j y_k) y^i. \quad (9)$$

Proof. The adapted components of the Cartan canonical connection are given by the general formulas (see [5])

$$\begin{aligned} L_{jk}^i &\stackrel{def}{=} \frac{g^{ir}}{2} \left(\frac{\delta g_{jr}}{\delta x^k} + \frac{\delta g_{kr}}{\delta x^j} - \frac{\delta g_{jk}}{\delta x^r} \right), \\ C_{jk}^i &\stackrel{def}{=} \frac{g^{ir}}{2} \left(\frac{\partial g_{jr}}{\partial y^k} + \frac{\partial g_{kr}}{\partial y^j} - \frac{\partial g_{jk}}{\partial y^r} \right) = \frac{g^{ir}}{2} \frac{\partial g_{jr}}{\partial y^k}. \end{aligned}$$

Using the derivative operators (6), direct calculations lead us to the claimed results. \square

Proposition 3. *The Cartan canonical N -linear connection produced by the anisotropic optical Lagrangian (3) is characterized by three effective local torsion d -tensors, namely R_{jk}^i , P_{jk}^i , C_{jk}^i , where*

$$\begin{aligned}
R_{jk}^i &= y^i (y_j \gamma_{0k} - y_k \gamma_{0j}) \varphi + (\delta_j^i \gamma_{0k} - \delta_k^i \gamma_{0j}) \varepsilon + \eta^{is} (\gamma_{sk} y_j - \gamma_{sj} y_k) \omega \\
&+ y^i (y_j \gamma_k - \gamma_j y_k) (\gamma_s \gamma^s) \left[\frac{7\varphi}{\gamma} - \frac{6}{\tau^2} - 18\varphi \varepsilon + \varphi^2 \|y\|^2 + 2\varphi \omega - \varepsilon \phi \|y\|^2 \right] \\
&+ (\delta_j^i \gamma_k - \delta_k^i \gamma_j) (\gamma_s \gamma^s) \left[\frac{2\varepsilon}{\gamma} - \frac{\|y\|^2}{\sigma\tau} - 9\varepsilon^2 - \varphi \varepsilon \|y\|^2 \right] \\
&+ \gamma^i (y_j \gamma_k - \gamma_j y_k) \left[\frac{\omega}{\gamma} + \frac{2\|y\|^2}{\sigma^2} + \frac{2\omega}{\sigma\tau} + \frac{\varepsilon\gamma\|y\|^2}{2\sigma^3} + \omega^2 \right] \\
&- (\delta_j^i y_k - \delta_k^i y_j) (\gamma_s \gamma^s)^2 \varphi (\|y\|^2 + \omega + \varepsilon) - (\delta_j^i y_k - \delta_k^i y_j) (\gamma_s \gamma^s) \omega \varepsilon, \\
P_{jk}^i &= y^i y_j y_k \gamma_0 \left[12\varphi \gamma^2 \tau \left(\frac{1}{\sigma} - \sigma^2 \right) - \frac{9\gamma^3}{\sigma^2 \tau} - \frac{4\gamma^3}{\sigma\tau} \right] + (\delta_j^i y_k + \delta_k^i y_j) \gamma_0 \varphi \\
&+ y^i (y_j \gamma_k + \gamma_j y_k) \left[\varphi - \frac{2\gamma}{\sigma} + \frac{6\gamma^3 \|y\|^2}{\sigma\tau} \right] + y^i \eta_{jk} \gamma_0 \left[\varphi - \frac{2\gamma^3 \|y\|^2}{\sigma\tau} \right] \\
&+ (\delta_j^i \gamma_k + \delta_k^i \gamma_j) \left(-\frac{3\gamma^3 \|y\|^4}{2\sigma\tau} \right) + \gamma^i \eta_{jk} \frac{\gamma^3 \|y\|^4}{2\sigma^2} + \gamma^i y_j y_k \frac{\gamma(4\sigma^2 - 1)}{2\sigma^3} \\
&+ (\delta_j^i N_{k0} + \delta_k^i N_{j0} - \eta^{ii} \eta_{jk} N_{i0}) \frac{\gamma^2}{\sigma} - y^i (N_{kj} + N_{jk}) \left(\frac{2\gamma^4}{\sigma\tau} - \frac{\gamma^2}{\sigma} \right) \\
&+ [(N_j^i - \eta^{ii} N_{ij}) y_k + ((N_k^i - \eta^{ii} N_{ik}) y_j)] \frac{\gamma^2}{\sigma} \\
&- (y^i N_{j0} y_k + y^i y_j N_{k0}) \frac{4\gamma^4}{\sigma\tau} + (y^i \eta_{jk} N_{00} + y^i y_j N_{0k} + y^i N_{0j} y_k) \frac{2\gamma^4}{\sigma\tau},
\end{aligned}$$

where

$$\begin{aligned}
\varphi &= \frac{\gamma(12\sigma^2 - 6\sigma + 1)}{4\sigma^2 \tau^2} \\
\varepsilon &= \frac{\gamma \|y\|^2 (2\tau + 1)}{4\sigma\tau} \\
\phi &= \frac{\gamma^3(12\sigma - 3)}{\sigma^3 \tau^2} - \frac{12\sigma^2 \gamma^2 \varphi}{\tau} \\
\omega &= -\frac{\gamma \|y\|^2 (2\sigma + 1)}{4\sigma^2}.
\end{aligned}$$

Proof. The local components of the torsion tensor are given by the general formulas (see [5])

$$R_{jk}^i = \frac{\delta N_j^i}{\delta x^k} - \frac{\delta N_k^i}{\delta x^j}, \quad P_{jk}^i = \frac{\partial N_j^i}{\partial y^k} - L_{kj}^i.$$

Using formula (4) and derivative operators (6), after laborious calculations we get the claimed results. \square

Acknowledgements. The present work was developed under the auspices of Grant AR-FRBCF 2565/2015–BRFFR–RA, No. F14RA-006, within the cooperation framework between Romanian Academy and Belarusian Republican Foundation for Fundamental Research.

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