

## ON A CLASS OF THREE DIMENSIONAL $f$ -KENMOTSU MANIFOLDS

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### Abstract

The curvature properties of three-dimensional  $f$ -Kenmotsu manifolds have been studied.

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## 1 Introduction

In 1972, K. Kenmotsu [9] introduced and studied a new class of almost contact metric manifolds, later known as Kenmotsu manifolds. Z. Olszak and R. Rosca [11] have studied  $f$ -Kenmotsu manifolds, an almost contact metric manifold which is normal and locally conformal almost cosymplectic. Further, they gave a geometric interpretation of  $f$ -Kenmotsu manifold and proved that a Ricci symmetric  $f$ -Kenmotsu manifold is an Einstein manifold. Recently,  $f$ -Kenmotsu manifolds have been studied by many authors in several ways to a different extent such as [12, 14, 15].

The projective curvature tensor is an important tensor from the differential geometric point of view. Let  $M$  be a  $(2n+1)$ -dimensional Riemannian manifold. If there exists a one to one correspondence between each coordinate neighbourhood of  $M$  and a domain in Euclidean space such that any geodesic of the Riemannian manifold corresponds to a straight line in the Euclidean space, then  $M$  is said to be locally projectively flat. For  $n \geq 1$ ,  $M$  is locally projectively flat if and only if the well known projective curvature tensor  $P$  vanishes, the projective curvature tensor is defined by [1, 13]

$$P(X, Y)Z = R(X, Y)Z - \frac{1}{2n}[S(Y, Z)X - S(X, Z)Y], \quad (1)$$

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where  $X, Y, Z \in \chi(M)$ ,  $R$  is the curvature tensor and  $S$  is the Ricci tensor with respect to the Levi-Civita connection.

A Ricci soliton  $(g, V, \lambda)$  on a Riemannian manifold  $(M, g)$  is a generalization of an Einstein metric such that [5, 7, 10]

$$(\mathcal{L}_V g + 2S + 2\lambda g)(X, Y) = 0, \quad (2)$$

where  $S$  is the Ricci tensor,  $\mathcal{L}_V$  is the Lie derivative operator along the vector field  $V$  on  $M$  and  $\lambda$  is a real number. The Ricci soliton is said to be shrinking, steady and expanding accordingly as  $\lambda$  is negative, zero and positive, respectively. Ricci solitons, in the context of general relativity, have been studied by M. Ali and Z. Ahsan [2 – 4].

Motivated by the above studies, in this paper we study some curvature properties of 3-dimensional  $f$ -Kenmotsu manifolds. The paper is organized as follows: In Section 2, we give a brief account of an  $f$ -Kenmotsu manifold. In Section 3, we show that a projectively flat 3-dimensional  $f$ -Kenmotsu manifold is an Einstein manifold of constant curvature  $-(f^2 + f')$ . Section 4 is devoted to study  $\phi$ -projectively semisymmetric 3-dimensional  $f$ -Kenmotsu manifolds. In Section 5, we discuss projectively semisymmetric 3-dimensional  $f$ -Kenmotsu manifolds. In Section 6, we show that a 3-dimensional  $f$ -Kenmotsu manifold satisfying the condition  $P \cdot S = 0$  is an Einstein manifold. Moreover, the fact that a 3-dimensional  $f$ -Kenmotsu manifold satisfying the condition  $S \cdot R = 0$  is an  $\eta$ -Einstein manifold is shown in Section 7. In Section 8, we show that a 3-dimensional  $f$ -Kenmotsu manifold admitting Ricci soliton is an  $\eta$ -Einstein manifold and the Ricci soliton is shrinking, steady and expanding if  $r + 2f > 0$ ,  $r + 2f = 0$  and  $r + 2f < 0$ , respectively. Finally, we give an example of 3-dimensional  $f$ -Kenmotsu manifold.

## 2 $f$ -Kenmotsu manifolds

Let  $M$  be a real  $(2n + 1)$ -dimensional differentiable manifold endowed with an almost contact metric structure  $(\phi, \xi, \eta, g)$  which satisfies

$$\phi^2 = -I + \eta \otimes \xi, \quad \eta(\xi) = 1, \quad (3)$$

$$\phi\xi = 0, \quad \eta \circ \phi = 0, \quad \eta(X) = g(X, \xi), \quad (4)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y) \quad (5)$$

for all vector fields  $X, Y \in \chi(M)$ , where  $I$  is the identity of the tangent bundle  $TM$ ,  $\phi$  is a tensor field of  $(1, 1)$  type,  $\eta$  is a 1-form,  $\xi$  is a vector field and  $g$  is a metric tensor field. We say that  $(M, \phi, \xi, \eta, g)$  is an  $f$ -Kenmotsu manifold if the Levi-Civita connection of  $g$  satisfies

$$(\nabla_X \phi)(Y) = f[g(\phi X, Y)\xi - \eta(Y)\phi X], \quad (6)$$

where  $f \in C^\infty(M)$  is strictly positive and  $df \wedge \eta = 0$ . If  $f = 0$ , then the manifold is cosymplectic [8]. An  $f$ -Kenmotsu manifold is said to be regular if  $f^2 + f' \neq 0$ ,

where  $f' = \xi f$ .

In an  $f$ -Kenmotsu manifold, from (6) we have

$$\nabla_X \xi = f[X - \eta(X)\xi]. \quad (7)$$

The condition  $df \wedge \eta = 0$  holds if  $\dim M \geq 5$ . This does not hold in general if  $\dim M = 3$  [14]

$$(\nabla_X \eta)Y = f[g(X, Y) - \eta(X)\eta(Y)]. \quad (8)$$

In a 3-dimensional Riemannian manifold, we have

$$\begin{aligned} R(X, Y)Z &= g(Y, Z)QX - g(X, Z)QY + S(Y, Z)X - S(X, Z)Y \\ &\quad - \frac{r}{2}[g(Y, Z)X - g(X, Z)Y]. \end{aligned} \quad (9)$$

In a 3-dimensional  $f$ -Kenmotsu manifold, we have

$$\begin{aligned} R(X, Y)Z &= \left(\frac{r}{2} + 2f^2 + 2f'\right)[g(Y, Z)X - g(X, Z)Y] \\ &\quad - \left(\frac{r}{2} + 3f^2 + 3f'\right)[g(Y, Z)\eta(X)\xi - g(X, Z)\eta(Y)\xi + \eta(Y)\eta(Z)X - \eta(X)\eta(Z)Y], \\ S(X, Y) &= \left(\frac{r}{2} + f^2 + f'\right)g(X, Y) - \left(\frac{r}{2} + 3f^2 + 3f'\right)\eta(X)\eta(Y), \end{aligned} \quad (10)$$

where  $R, S, Q$  and  $r$  are the Riemann curvature tensor, the Ricci tensor, the Ricci operator and the scalar curvature, respectively.

Now from (10), we find

$$R(X, Y)\xi = -(f^2 + f')[\eta(Y)X - \eta(X)Y], \quad (12)$$

$$R(\xi, X)Y = -(f^2 + f')[g(X, Y)\xi - \eta(Y)X], \quad (13)$$

$$R(X, \xi)\xi = -(f^2 + f')[X - \eta(X)\xi], \quad (14)$$

$$\eta(R(X, Y)Z) = -(f^2 + f')[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)]. \quad (15)$$

And from (11), we get

$$S(X, \xi) = -2(f^2 + f')\eta(X), \quad (16)$$

$$Q\xi = -2(f^2 + f')\xi. \quad (17)$$

**Definition 1.** An  $f$ -Kenmotsu manifold is said to be an  $\eta$ -Einstein manifold if the Ricci tensor  $S$  of type  $(0, 2)$  is of the form

$$S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y), \quad (18)$$

where  $a$  and  $b$  are smooth functions on  $M$ . In particular, if  $b = 0$ , then the manifold is said to be an Einstein manifold.

### 3 Projectively flat 3-dimensional $f$ -Kenmotsu manifolds

Let  $M$  be a projectively flat 3-dimensional  $f$ -Kenmotsu manifold, that is,  $P = 0$ . Then from (1), it follows that

$$R(X, Y)Z = \frac{1}{2}[S(Y, Z)X - S(X, Z)Y]. \quad (19)$$

Taking inner product of (19) with  $\xi$  and using (4), we have

$$g[R(X, Y)Z, \xi] = \frac{1}{2}[S(Y, Z)\eta(X) - S(X, Z)\eta(Y)]. \quad (20)$$

Putting  $X = \xi$  in (20) and using (3), (13) and (16), we get

$$S(Y, Z) = -2(f^2 + f')g(Y, Z). \quad (21)$$

Now using (21) in (19), we obtain

$$R(X, Y)Z = -(f^2 + f')[g(Y, Z)X - g(X, Z)Y] \quad (22)$$

which can be written as

$$g[R(X, Y)Z, U] = -(f^2 + f')[g(Y, Z)g(X, U) - g(X, Z)g(Y, U)]. \quad (23)$$

Thus we can state the following:

**Theorem 1.** *A projectively flat 3-dimensional  $f$ -Kenmotsu manifold is an Einstein manifold of constant curvature  $-(f^2 + f')$  and consequently it is locally isometric to the Hyperbolic space  $H^3[-(f^2 + f')]$ .*

### 4 $\phi$ -projectively semisymmetric 3-dimensional $f$ -Kenmotsu manifolds

**Definition 2.** *A 3-dimensional  $f$ -Kenmotsu manifold is said to be  $\phi$ -projectively semisymmetric if [6]*

$$P(X, Y) \cdot \phi = 0$$

for all  $X, Y \in \chi(M)$ .

Let  $M$  be a  $\phi$ -projectively semisymmetric 3-dimensional  $f$ -Kenmotsu manifold. Therefore  $P(X, Y) \cdot \phi = 0$  turns into

$$(P(X, Y) \cdot \phi)Z = P(X, Y)\phi Z - \phi P(X, Y)Z = 0 \quad (24)$$

for any vector fields  $X, Y, Z \in \chi(M)$ . From (1), we write

$$P(X, Y)\phi Z = R(X, Y)\phi Z - \frac{1}{2}[S(Y, \phi Z)X - S(X, \phi Z)Y] \quad (25)$$

and

$$\phi P(X, Y)Z = \phi R(X, Y)Z - \frac{1}{2}[S(Y, Z)\phi X - S(X, Z)\phi Y]. \quad (26)$$

Now combining (24), (25) and (26), we have

$$\begin{aligned} R(X, Y)\phi Z - \phi R(X, Y)Z - \frac{1}{2}[S(Y, \phi Z)X - S(X, \phi Z)Y] \\ + \frac{1}{2}[S(Y, Z)\phi X - S(X, Z)\phi Y] = 0. \end{aligned} \quad (27)$$

Taking  $X = \xi$  in (27) and then using (4), (11), (13) and (16), we get

$$r = -6(f^2 + f'), \quad g(Y, \phi Z) \neq 0. \quad (28)$$

Using this value of  $r$  in (11), we obtain

$$S(Y, Z) = -2(f^2 + f')g(Y, Z). \quad (29)$$

Thus in view of (10), (28) and (29), we have the following:

**Theorem 2.** *In a 3-dimensional  $f$ -Kenmotsu manifold  $M$ , the following conditions are equivalent:*

- (a)  $\phi$ -projectively semisymmetric,
- (b) the scalar curvature  $r = -6(f^2 + f')$ ,
- (c) the manifold  $M$  is of constant curvature,
- (d)  $M$  is an Einstein manifold.

## 5 Projectively semisymmetric 3-dimensional $f$ -Kenmotsu manifolds

In this section, we suppose that a 3-dimensional  $f$ -Kenmotsu manifold is projectively semisymmetric, that is,

$$(R(X, Y) \cdot P)(U, V)W = 0$$

for any vector fields  $X, Y, U, V$  and  $W \in \chi(M)$ . This implies that

$$\begin{aligned} R(X, Y)P(U, V)W - P(R(X, Y)U, V)W - P(U, R(X, Y)V)W \\ - P(U, V)R(X, Y)W = 0. \end{aligned} \quad (30)$$

Putting  $U = W = Y = \xi$  in (30), we have

$$R(X, \xi)P(\xi, V)\xi - P(R(X, \xi)\xi, V)\xi - P(\xi, R(X, \xi)V)\xi - P(\xi, V)R(X, \xi)\xi = 0$$

which in view of (1), (13) and (14) reduces to

$$P(\xi, V)R(X, \xi)\xi = 0$$

which by using (14) gives

$$P(\xi, V)X = 0, \quad \text{as } f^2 + f' \neq 0.$$

This implies that

$$R(\xi, V)X - \frac{1}{2}[S(V, X)\xi - S(\xi, X)V] = 0. \quad (31)$$

By virtue of (11), (13) and (16), (31) takes the form

$$\left(\frac{r}{2} + 3f^2 + 3f'\right)[g(V, X)\xi - \eta(X)\eta(V)\xi] = 0. \quad (32)$$

Now by replacing  $X$  by  $\phi X$ ,  $V$  by  $\phi V$  in (32) and using (5), we get

$$r = -6(f^2 + f'). \quad (33)$$

Using this value of  $r$  in (11), we obtain

$$S(Y, Z) = -2(f^2 + f')g(Y, Z). \quad (34)$$

Thus in view of (10), (33) and (34), we have the following:

**Theorem 3.** *In a 3-dimensional  $f$ -Kenmotsu manifold  $M$ , the following conditions are equivalent:*

- (a) *projectively semisymmetric,*
- (b) *the scalar curvature  $r = -6(f^2 + f')$ ,*
- (c) *the manifold  $M$  is of constant curvature,*
- (d)  *$M$  is an Einstein manifold.*

## 6 3-dimensional $f$ -Kenmotsu manifolds satisfying $P \cdot S = 0$

In this section, we study a 3-dimensional  $f$ -Kenmotsu manifold satisfying the condition  $P \cdot S = 0$ . Therefore we have

$$(P(X, Y) \cdot S)(U, V) = 0$$

for any vector fields  $X, Y, U$  and  $V \in \chi(M)$ . This implies that

$$S(P(X, Y)U, V) + S(U, P(X, Y)V) = 0. \quad (35)$$

Putting  $U = \xi$  in (35), we have

$$S(P(X, Y)\xi, V) + S(\xi, P(X, Y)V) = 0$$

which by using the fact that  $P(X, Y)\xi = 0$  reduces to

$$S(\xi, P(X, Y)V) = 0. \tag{36}$$

In view of (16), (36) becomes

$$g[R(X, Y)V, \xi] - \frac{1}{2}[S(Y, V)\eta(X) - S(X, V)\eta(Y)] = 0. \tag{37}$$

Taking  $Y = \xi$  in (37) and using (3), (13) and (16), we obtain

$$S(Y, Z) = -2(f^2 + f')g(Y, Z).$$

Thus we have the following:

**Theorem 4.** *A 3-dimensional  $f$ -Kenmotsu manifold satisfying  $P \cdot S = 0$  is an Einstein manifold.*

## 7 3-dimensional $f$ -Kenmotsu manifolds satisfying $S \cdot R = 0$

In this section, we study a 3-dimensional  $f$ -Kenmotsu manifold satisfying the condition

$$(S(X, Y) \cdot R)(U, V)W = 0$$

for any vector fields  $X, Y, U, V$  and  $W \in \chi(M)$ . Therefore we have

$$\begin{aligned} (X_{\wedge S}Y)R(U, V)W + R((X_{\wedge S}Y)U, V)W + R(U, (X_{\wedge S}Y)V)W \\ + R(U, V)(X_{\wedge S}Y)W = 0, \end{aligned} \tag{38}$$

where the endomorphism  $X_{\wedge S}Y$  is defined by

$$(X_{\wedge S}Y)W = S(Y, W)X - S(X, W)Y. \tag{39}$$

Taking  $Y = \xi$  in (38) and using (39), we have

$$\begin{aligned} 2(f^2 + f')[\eta(R(U, V)W)X + \eta(U)R(X, V)W + \eta(V)R(U, X)W \\ + \eta(W)R(U, V)X] + S[X, R(U, V)W]\xi + S(X, U)R(\xi, V)W \\ + S(X, V)R(U, \xi)W + S(X, W)R(U, V)\xi = 0 \end{aligned}$$

which by taking inner product with  $\xi$  and using (4) takes the form

$$2(f^2 + f')[\eta(R(U, V)W)\eta(X) + \eta(U)\eta(R(X, V)W) + \eta(V)\eta(R(U, X)W)] \tag{40}$$

$$\begin{aligned}
& +\eta(W)\eta(R(U, V)X)] + S[X, R(U, V)W] + S(X, U)\eta(R(\xi, V)W) \\
& + S(X, V)\eta(R(U, \xi)W) + S(X, W)\eta(R(U, V)\xi) = 0.
\end{aligned}$$

Now taking  $U = W = \xi$  in (40) and using (3), (12), (13) and (16), we get

$$S(X, V) = 2(f^2 + f')g(X, V) - 4(f^2 + f')\eta(X)\eta(V). \quad (41)$$

Contracting (41) over  $X$  and  $V$ , we obtain

$$r = 2(f^2 + f').$$

Thus we have the following:

**Theorem 5.** *A 3-dimensional  $f$ -Kenmotsu manifold satisfying  $S \cdot R = 0$  is an  $\eta$ -Einstein manifold with the scalar curvature  $2(f^2 + f')$ .*

## 8 Ricci solitons in 3-dimensional $f$ -Kenmotsu manifolds

Suppose that a 3-dimensional  $f$ -Kenmotsu manifold admits a Ricci soliton. Then

$$(\mathcal{L}_V g + 2S + 2\lambda g)(X, Y) = 0$$

which implies that

$$g(\nabla_X \xi, Y) + g(X, \nabla_Y \xi) + 2S(X, Y) + 2\lambda g(X, Y) = 0. \quad (42)$$

By using (7) in (42), we have

$$S(X, Y) + (\lambda + f)g(X, Y) - f\eta(X)\eta(Y) = 0. \quad (43)$$

Contracting (43) over  $X$  and  $Y$  yields

$$\lambda = -\frac{r + 2f}{3}. \quad (44)$$

Putting this value of  $\lambda$  in (43), we obtain

$$S(X, Y) = \left(\frac{r - f}{3}\right)g(X, Y) + f\eta(X)\eta(Y). \quad (45)$$

Thus we can state the following:

**Theorem 6.** *If a 3-dimensional  $f$ -Kenmotsu manifold admits a Ricci soliton, then the manifold is an  $\eta$ -Einstein manifold and its Ricci soliton is shrinking, steady or expanding accordingly as  $r + 2f > 0$ ,  $r + 2f = 0$  or  $r + 2f < 0$ , respectively.*

**Example of a 3-dimensional  $f$ -Kenmotsu manifold.** We consider the 3-dimensional manifold  $M = \{(x, y, z) \in R^3\}$ , where  $(x, y, z)$  are the standard coordinates in  $R^3$ . Let  $e_1, e_2$  and  $e_3$  be the vector fields on  $M$  given by

$$e_1 = e^{-2z} \frac{\partial}{\partial x}, \quad e_2 = e^{-2z} \frac{\partial}{\partial y}, \quad e_3 = e^{-z} \frac{\partial}{\partial z} = \xi,$$

which are linearly independent at each point of  $M$  and hence form a basis of  $T_p M$ . Let  $g$  be the Riemannian metric defined by

$$g(e_1, e_1) = g(e_2, e_2) = g(e_3, e_3) = 1, \quad g(e_1, e_2) = g(e_1, e_3) = g(e_2, e_3) = 0.$$

Let  $\eta$  be the 1-form on  $M$  defined as  $\eta(X) = g(X, e_3) = g(X, \xi)$  for all  $X \in \chi(M)$ , and let  $\phi$  be the  $(1, 1)$  tensor field on  $M$  defined as

$$\phi e_1 = -e_2, \quad \phi e_2 = e_1, \quad \phi e_3 = 0.$$

By applying linearity of  $\phi$  and  $g$ , we have

$$\begin{aligned} \eta(\xi) &= g(\xi, \xi) = 1, \quad \phi^2 X = -X + \eta(X)\xi, \quad \eta(\phi X) = 0, \\ g(X, \xi) &= \eta(X), \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y) \end{aligned}$$

for all  $X, Y \in \chi(M)$ .

Now, by direct computations we obtain

$$[e_1, e_2] = 0, \quad [e_3, e_1] = -2e^{-z}e_1, \quad [e_2, e_3] = 2e^{-z}e_2.$$

The Riemannian connection  $\nabla$  of the metric tensor  $g$  is given by

$$\begin{aligned} 2g(\nabla_X Y, Z) &= Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) - g(X, [Y, Z]) + g(Y, [Z, X]) \\ &\quad + g(Z, [X, Y]), \end{aligned}$$

which is known as Koszul's formula. Using Koszul's formula, we can easily calculate

$$\begin{aligned} \nabla_{e_1} e_1 &= -2e^{-z}e_3, \quad \nabla_{e_1} e_2 = 0, \quad \nabla_{e_1} e_3 = 2e^{-z}e_1, \quad \nabla_{e_2} e_1 = 0, \\ \nabla_{e_2} e_2 &= -2e^{-z}e_3, \quad \nabla_{e_2} e_3 = 2e^{-z}e_2, \quad \nabla_{e_3} e_1 = 0, \quad \nabla_{e_3} e_2 = 0, \quad \nabla_{e_3} e_3 = 0. \end{aligned}$$

$$\text{Let } X = \sum_{i=1}^3 X^i e_i = X^1 e_1 + X^2 e_2 + X^3 e_3 \in \chi(M).$$

It can be easily verified that the manifold satisfies

$$\nabla_X \xi = f[X - \eta(X)\xi] \quad \text{and} \quad (\nabla_X \phi)Y = f[g(\phi X, Y)\xi - \eta(Y)\phi X]$$

for  $\xi = e_3$ , where  $f = 2e^{-z}$ .

Hence we conclude that  $M$  is a 3-dimensional  $f$ -Kenmotsu manifold. Also  $f^2 + f' \neq 0$ . Hence  $M$  is a regular  $f$ -Kenmotsu manifold.

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