

STUDY ON GENERALIZED PSEUDO (RICCI) SYMMETRIC SASAKIAN MANIFOLD ADMITTING GENERAL CONNECTION

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Abstract

The object of the present paper is to study the generalized pseudo (Ricci) symmetric Sasakian manifold with respect to a new connection named general connection. The general connection has the flavour of quarter-symmetric connection, generalized Tanaka-Webster connection, Zamkovoy and Schouten-van Kampen connection. The existence of generalized pseudo (Ricci) symmetric Sasakian manifold with respect to general connection is ensured by an example.

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1 Introduction

Let the symbols ∇ , ∇^q , ∇^T , ∇^z , ∇^s and ∇^* stand for Levi-civita connection, quarter-symmetric metric connection, Generalized Tanaka-Webster connection, Zamkovoy connection, Schouten-Van Kampen connection and general connections respectively. Also we denote $(GPS)_n$ and $(GPRS)_n$ for generalized pseudo symmetric Sasakian manifold and generalized pseudo Ricci symmetric Sasakian manifold. In 1924, A. Friedmann and J. A. Schouten[1] founded the idea of semi-symmetric connection on a differentiable manifold. In 1932, H. A. Hayden[8] further studied the thought of semi-symmetric connection with torsion on a Riemannian manifold. A comprehensive study of Semi-symmetric metric connection was carried out by Yano[21]. Semi-symmetric metric connection plays a vital role in Riemannian geometry. Generalising the concept of semi-symmetric connection

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Golab[7] defined and studied the quarter-symmetric connection in 1975. There after, many geometers like as Rastogi ([13], [14]), Mishra et al. [11], Yano et al.[20] and others studied quarter symmetric connection. An affine connection ∇^q on an n -dimensional Riemannian manifold (M, g) is called a quarter-symmetric connection[7] if its torsion tensor T of the connection ∇^q satisfies

$$\begin{aligned} T(X, Y) &= \nabla_X^q Y - \nabla_Y^q X - [X, Y] \\ &= \eta(Y)\phi X - \eta(X)\phi Y, \end{aligned}$$

where η is a 1-form and ϕ is a $(1, 1)$ tensor field. In particular, if $\phi X = X$, then the quarter-symmetric connection reduces to the semi-symmetric connection[1]. Furthermore, if a quarter-symmetric connection ∇^q admits the condition

$$(\nabla_X^q g)(Y, Z) = 0,$$

then ∇^q is said to be a quarter-symmetric metric connection, otherwise it is said to be a quarter-symmetric non-metric connection. If ∇ and ∇^q are the Levi-civita connection and quarter-symmetric connection respectively, then

$$\nabla_X^q Y = \nabla_X Y - \eta(X)\phi Y. \quad (1)$$

In 1970 Tanno[18] characterized and considered the idea of summed up Tanaka-Webster connection by summing up the connection by Tanaka [12] and Webster[17], which harmonizes with the Tanaka-Webster connection if the related contact Riemann structure is integrable. Likewise J. T. Cho([9],[10]) has considered the Generalized Tanaka-Webster connection with regards to Kahler manifold. Let ∇ and ∇^T be the Levi-civita connection and generalized Tanaka-Webster connection respectively. Then

$$\nabla_X^T Y = \nabla_X Y + (\nabla_X \eta)(Y)\xi - \eta(Y)\nabla_X \xi - \eta(X)\phi Y. \quad (2)$$

Also Z. Zamkovoy[22] has introduced a new connection known as Zamkovoy connection ∇^z , which is related with Levi-civita connection as

$$\nabla_X^z Y = \nabla_X Y + (\nabla_X \eta)(Y)\xi - \eta(Y)\nabla_X \xi + \eta(X)\phi Y. \quad (3)$$

Schouten, J. A. and Van Kampen[16] introduced the Schouten-van Kampen connection in the third decade of last century. The relation[16] between Schouten-van Kampen connection ∇^s and Levi-Civita connection ∇ is

$$\nabla_X^s Y = \nabla_X Y + (\nabla_X \eta)(Y)\xi - \eta(Y)\nabla_X \xi. \quad (4)$$

In the setting of Sasakian geometry, we like to define a new connection named general connection ∇^* , which is related with ∇

$$\nabla_X^* Y = \nabla_X Y + \lambda[(\nabla_X \eta)(Y)\xi - \eta(Y)\nabla_X \xi] + \mu\eta(X)\phi Y, \quad (5)$$

for all $X, Y \in \chi(M)$ and the pair (λ, μ) being real constants. Connection defined in (5) has an important characteristic because it has a flavour of quarter symmetric metric connection for $(\lambda, \mu) \equiv (0, -1)$; Tanaka Webster connection for

$(\lambda, \mu) \equiv (1, -1)$; Zamkovoy connection for $(\lambda, \mu) \equiv (1, 1)$; Schouten Kampen-Van connection $(\lambda, \mu) \equiv (1, 0)$.

This paper is structured as follows: After the introduction, section 2, we give a brief account of the Sasakian manifolds. Section 3 is dedicated to establishing the relation between the curvature tensor of the Sasakian manifolds with respect to the general connection and the levi-civita connection. Section 4 is concerned with generalized pseudo symmetric Sasakian manifolds admitting general connection and we prove that there exists no generalized pseudo symmetric Sasakian manifold with respect to general connection unless $\beta - \bar{C}\alpha$ vanishes everywhere, provided $\bar{C} \neq 0$. It is worthy to note that there exists no $[(GPS)_n, \nabla^T]$, $[(GPS)_n, \nabla^s]$, $[(GPS)_n, \nabla^z]$ unless β vanishes everywhere. In the next section, we investigate the generalized pseudo Ricci-symmetric Sasakian manifolds admitting general connection. Finally, we construct an example for the existence of generalized pseudo symmetric and generalized pseudo Ricci-symmetric Sasakian manifolds with respect to the general connection.

2 Preliminaries

Let M be an n -dimensional almost contact metric manifold equipped with an almost contact metric structure (ϕ, ξ, η, g) consisting of a $(1, 1)$ tensor field ϕ , a vector field ξ , a 1-form η and a Riemannian metric g . Then

$$\phi^2 Y = -Y + \eta(Y)\xi, \eta(\xi) = 1, \eta(\phi X) = 0, \phi\xi = 0, \tag{6}$$

$$g(X, Y) = g(\phi X, \phi Y) + \eta(X)\eta(Y), \tag{7}$$

$$g(X, \phi Y) = -g(\phi X, Y), \eta(Y) = g(Y, \xi), \forall X, Y \in TM. \tag{8}$$

An almost contact metric manifold M is said to be (a) a contact metric manifold if

$$g(X, \phi Y) = d\eta(X, Y), \forall X, Y \in TM; \tag{9}$$

(b) a K -contact manifold if the vector field ξ is Killing equivalently

$$\nabla_Y \xi = -\phi Y, \tag{10}$$

where ∇ is Riemannian connection and (c) a Sasakian manifold if

$$(\nabla_X \phi)Y = g(X, Y)\xi - \eta(Y)X, \forall X, Y \in TM. \tag{11}$$

A K -contact manifold is a contact metric manifold, while the converse is true if the Lie derivative of ϕ in the characteristic direction ξ vanishes identically. A Sasakian manifold is always a K -contact manifold. A 3-dimensional K -contact manifold is a Sasakian manifold.

It is well known that a contact metric manifold is Sasakian if and only if

$$R(X, Y)\xi = \eta(Y)X - \eta(X)Y, \forall X, Y \in TM. \tag{12}$$

In a Sasakian manifold equipped with the structure (ϕ, ξ, η, g) , the following relations also hold ([2], [19], [15]):

$$(\nabla_X \eta) Y = g(X, \phi Y), \quad (13)$$

$$R(\xi, X) Y = g(X, Y) \xi - \eta(Y) X, \quad (14)$$

$$S(X, \xi) = (n-1) \eta(X), \quad (15)$$

$$R(X, \xi) Y = \eta(Y) X - g(X, Y) \xi, \quad (16)$$

$$Q\xi = (n-1) \xi \quad (17)$$

3 Some properties of Sasakian manifold admitting general connection

In Sasakian manifold, the relation (5) reduces to

$$\nabla_X^* Y = \nabla_X Y + \lambda [g(X, \phi Y) \xi + \eta(Y) \phi X] + \mu \eta(X) \phi Y. \quad (18)$$

Putting $Y = \xi$ in (5)

$$\nabla_X^* \xi = -\phi X + \lambda \phi X. \quad (19)$$

Now with the help of (18), (10) and (11) we get the followings

$$\begin{aligned} & \nabla_X^* \eta(Y) \\ &= \nabla_X^* g(Y, \xi) \\ &= \eta(\nabla_X Y) + \lambda g(X, \phi Y) - g(Y, \phi X) + \lambda g(Y, \phi X), \end{aligned} \quad (20)$$

$$\begin{aligned} & \nabla_X^* (\phi Y) \\ &= \nabla_X (\phi Y) - \lambda g(\phi X, \phi Y) \xi - \mu \eta(X) Y + \mu \eta(X) \eta(Y) \xi, \end{aligned} \quad (21)$$

$$\begin{aligned} & \nabla_X^* g(Y, \phi Z) \\ &= g(\nabla_X Y, \phi Z) + \mu \eta(X) g(\phi Y, \phi Z) + g(Y, \nabla_X (\phi Z)) \\ & \quad - \mu \eta(X) g(Y, Z) + \mu \eta(X) \eta(Y) \eta(Z). \end{aligned} \quad (22)$$

Now we know that

$$R^*(X, Y) Z = \nabla_X^* \nabla_Y^* Z - \nabla_Y^* \nabla_X^* Z - \nabla_{[X, Y]}^* Z. \quad (23)$$

By using (18), (19), (20), (21) and (22) we obtain the following

$$\begin{aligned}
 & \nabla_X^* \nabla_Y^* Z \\
 = & \nabla_X \nabla_Y Z + \lambda g(X, \phi \nabla_Y Z) \xi + \lambda \eta(\nabla_Y Z) \phi X + \mu \eta(X) \phi \nabla_Y Z \\
 & + \lambda g(\nabla_X Y, \phi Z) \xi + \lambda \mu \eta(X) g(\phi Y, \phi Z) \xi + \lambda g(Y, \nabla_X(\phi Z)) \xi \\
 & - \lambda \mu \eta(X) g(Y, Z) \xi + \lambda \mu \eta(X) \eta(Y) \eta(Z) \xi - \lambda g(Y, \phi Z) \phi X \\
 & + \lambda^2 g(Y, \phi Z) \phi X + \lambda \eta(\nabla_X Z) \phi Y + \lambda^2 g(X, \phi Z) \phi Y \\
 & + \lambda^2 g(Z, \phi X) \phi Y + \lambda \eta(Z) \nabla_X(\phi Y) - \lambda^2 \eta(Z) g(\phi X, \phi Y) \xi \\
 & - \lambda \mu \eta(Z) \eta(X) Y + \lambda \mu \eta(Z) \eta(X) \eta(Y) \xi + \mu \eta(\nabla_X Y) \phi Z \\
 & + \lambda \mu g(X, \phi Y) \phi Z - \mu g(Y, \phi X) \phi Z + \lambda \mu g(Y, \phi X) \phi Z \\
 & + \mu \eta(Y) \nabla_X(\phi Z) - \lambda \mu \eta(Y) g(\phi X, \phi Z) \xi - \lambda g(Z, \phi X) \phi Y \\
 & - \mu^2 \eta(Y) \eta(X) Z + \mu^2 \eta(Y) \eta(X) \eta(Z) \xi,
 \end{aligned} \tag{24}$$

$$\begin{aligned}
 & \nabla_Y^* \nabla_X^* Z \\
 = & \nabla_Y \nabla_X Z + \lambda g(Y, \phi \nabla_X Z) \xi + \lambda \eta(\nabla_X Z) \phi Y + \mu \eta(Y) \phi \nabla_X Z \\
 & + \lambda g(\nabla_Y X, \phi Z) \xi + \lambda \mu \eta(Y) g(\phi X, \phi Z) \xi + \lambda g(X, \nabla_Y(\phi Z)) \xi \\
 & - \lambda \mu \eta(Y) g(X, Z) \xi + \lambda \mu \eta(Y) \eta(X) \eta(Z) \xi - \lambda g(X, \phi Z) \phi Y \\
 & + \lambda^2 g(X, \phi Z) \phi Y + \lambda \eta(\nabla_Y Z) \phi X + \lambda^2 g(Y, \phi Z) \phi X \\
 & - \lambda g(Z, \phi Y) \phi X + \lambda^2 g(Z, \phi Y) \phi X + \lambda \eta(Z) \nabla_Y(\phi X) \\
 & - \lambda^2 \eta(Z) g(\phi Y, \phi X) \xi - \lambda \mu \eta(Z) \eta(Y) X + \lambda \mu \eta(Z) \eta(Y) \eta(X) \xi \\
 & + \mu \eta(\nabla_Y X) \phi Z + \lambda \mu g(Y, \phi X) \phi Z - \mu g(X, \phi Y) \phi Z \\
 & + \lambda \mu g(X, \phi Y) \phi Z + \mu \eta(X) \nabla_Y(\phi Z) - \lambda \mu \eta(X) g(\phi Y, \phi Z) \xi \\
 & - \mu^2 \eta(X) \eta(Y) Z + \mu^2 \eta(X) \eta(Y) \eta(Z) \xi,
 \end{aligned} \tag{25}$$

and

$$\begin{aligned}
 & \nabla_{[X,Y]}^* Z \\
 = & \nabla_{[X,Y]} Z + \lambda g(\nabla_X Y, \phi Z) \xi - \lambda g(\nabla_Y X, \phi Z) \xi + \lambda \eta(Z) \phi \nabla_X Y \\
 & - \lambda \eta(Z) \phi \nabla_Y X + \mu \eta(\nabla_X Y) \phi Z - \mu \eta(\nabla_Y X) \phi Z.
 \end{aligned} \tag{26}$$

Now in reference of (24), (25) and (26) we get from (23)

$$\begin{aligned}
 & R^*(X, Y) Z \\
 = & R(X, Y) Z + (\lambda^2 - 2\lambda) [g(Z, \phi X) \phi Y + g(Y, \phi Z) \phi X] \\
 & - 2\mu g(Y, \phi X) \phi Z \\
 & + (\lambda - \lambda\mu + \mu) [g(X, Z) \eta(Y) \xi - \eta(X) g(Y, Z) \xi] \\
 & + (\lambda - \lambda\mu + \mu) [\eta(X) \eta(Z) Y - \eta(Y) \eta(Z) X]
 \end{aligned} \tag{27}$$

Consequently one can easily bring out the following

$$S^*(Y, Z) = S(Y, Z) - \bar{A}g(Y, Z) + \bar{B}\eta(Y)\eta(Z), \quad (28)$$

$$S^*(Y, \xi) = -(n-1)\bar{C}\eta(Y), \quad (29)$$

$$S^*(\xi, Z) = -(n-1)\bar{C}\eta(Z), \quad (30)$$

$$Q^*Y = QY - \bar{A}Y + \bar{B}\eta(Y)\xi, \quad (31)$$

$$Q^*\xi = -(n-1)\bar{C}\xi, \quad (32)$$

$$r^* = r - \bar{A}n + \bar{B}, \quad (33)$$

$$R^*(X, Y)\xi = \bar{C}[\eta(X)Y - \eta(Y)X], \quad (34)$$

$$R^*(\xi, Y)Z = \bar{C}[\eta(Z)Y - g(Y, Z)\xi], \quad (35)$$

$$R^*(X, \xi)Z = \bar{C}[g(X, Z)\xi - \eta(Z)X]. \quad (36)$$

where

$$\bar{A} = (\lambda^2 - \lambda - \mu - \lambda\mu), \quad (37)$$

$$\bar{B} = [\lambda^2 + (n-2)\lambda\mu - n(\lambda + \mu)], \quad (38)$$

$$\bar{C} = (\lambda - \lambda\mu + \mu - 1). \quad (39)$$

Therefore, for quarter-symmetric metric connection

$$\bar{A} = 1; \bar{B} = n; \bar{C} = -2, \quad (40)$$

Tanaka Webster connection

$$\bar{A} = 2; \bar{B} = 3 - n; \bar{C} = 0, \quad (41)$$

Zamkovoy connection

$$\bar{A} = -2; \bar{B} = -1 - n; \bar{C} = 0, \quad (42)$$

and for Schouten Kampen-Van connection

$$\bar{A} = 0; \bar{B} = 1 - n; \bar{C} = 0. \quad (43)$$

Thus, we can state the following

Proposition 1. *Let M be an n -dimensional Sasakian manifold admitting general connection ∇^* , Then*

- (i) *The curvature tensor R^* of ∇^* is given by (27),*
- (ii) *The Ricci tensor S^* of ∇^* is given by (28),*
- (iii) *The scalar curvature r^* of ∇^* is given by (33),*
- (iv) *The Ricci tensor S^* of ∇^* is symmetric.*

Now if we suppose that the Sasakian manifold is Ricci flat with respect to the general connection then from (28) we get

$$S(Y, Z) = \bar{A}g(Y, Z) - \bar{B}\eta(Y)\eta(Z).$$

This leads to the following

Theorem 1. *If manifold M^n is Ricci flat with respect to the general connection if and only if M^n is an η -Einstein manifold.*

4 Generalised pseudo symmetric Sasakian manifold with respect to general connection

A non-flat Sasakian manifold (M^n, g) ($n \geq 3$) is said to be pseudo symmetric[3], if the curvature tensor R satisfies the condition.

$$\begin{aligned} &(\nabla_X R)(U, V, W, Y) \\ = &2\alpha(X)R(U, V, W, Y) + \alpha(U)R(X, V, W, Y) \\ &+ \alpha(V)R(U, X, W, Y) + \alpha(W)R(U, V, X, Y) \\ &+ \alpha(Y)R(U, V, W, X). \end{aligned}$$

Keeping in tune with Dubey[6], a non-flat Sasakian manifold (M^n, g) ($n \geq 3$) is said to be generalized pseudo symmetric if the curvature tensor R satisfies the condition

$$\begin{aligned} &(\nabla_X R)(U, V, W, Y) \\ = &2\alpha(X)R(U, V, W, Y) + \alpha(U)R(X, V, W, Y) \\ &+ \alpha(V)R(U, X, W, Y) + \alpha(W)R(U, V, X, Y) \\ &+ \alpha(Y)R(U, V, W, X) + 2\beta(X)G(U, V, W, Y) \\ &+ \beta(U)G(X, V, W, Y) + \beta(V)G(U, X, W, Y) \\ &+ \beta(W)G(U, V, X, Y) + \beta(Y)G(U, V, W, X), \end{aligned} \tag{44}$$

where

$$G(Y, U, V, W) = [g(U, V)g(Y, W) - g(Y, V)g(U, W)]. \tag{45}$$

for all vectors fields $X, U, V \in \chi(M)$ and where non zero one forms α, β are defined by

$$\alpha(X) = g(X, \rho_1); \beta(X) = g(X, \rho_2). \tag{46}$$

Now we denote the generalised pseudo symmetric-Sasakian manifold with respect to the general connection by $([(GPS)_n, \nabla^*])$, whose curvature tensor satisfies the following condition

$$\begin{aligned} &(\nabla_X^* R^*)(U, V, W, Y) \\ = &2\alpha(X)R^*(U, V, W, Y) + \alpha(U)R^*(X, V, W, Y) \\ &+ \alpha(V)R^*(U, X, W, Y) + \alpha(W)R^*(U, V, X, Y) \\ &+ \alpha(Y)R^*(U, V, W, X) + 2\beta(X)G(U, V, W, Y) \\ &+ \beta(U)G(X, V, W, Y) + \beta(V)G(U, X, W, Y) \\ &+ \beta(W)G(U, V, X, Y) + \beta(Y)G(U, V, W, X) \end{aligned} \tag{47}$$

which yields after contraction,

$$\begin{aligned}
& (\nabla_X^* S^*) (V, W) \\
= & 2\alpha (X) S^* (V, W) + \alpha (R^* (X, V) W) \\
& + \alpha (V) S^* (X, W) + \alpha (W) S^* (V, X) \\
& - \alpha (R^* (W, X) V) + 2\beta (X) ng (V, W) \\
& - 2\beta (X) g (V, W) + \beta (X) g (V, W) \\
& - g (X, W) \beta (V) + \beta (V) ng (X, W) \\
& - \beta (V) g (X, W) + \beta (W) ng (V, X) \\
& - \beta (W) g (X, V) + \beta (X) g (V, W) \\
& - \beta (W) g (X, V). \tag{48}
\end{aligned}$$

Replacing W by ξ in (48), we get

$$\begin{aligned}
& (\nabla_X^* S^*) (V, \xi) \\
= & -2(n-1)\bar{C}\alpha(X)\eta(V) + \bar{C}\eta(X)\alpha(V) - \bar{C}\eta(V)\alpha(X) \\
& - (n-1)\bar{C}\alpha(V)\eta(X) + \alpha(\xi)S^*(V, X) \\
& - \bar{C}\eta(V)\alpha(X) + \bar{C}g(X, V)\alpha(\xi) + 2n\beta(X)\eta(V) \\
& - 2\beta(X)\eta(V) + \beta(X)\eta(V) - \eta(X)\beta(V) \\
& + \beta(V)n\eta(X) - \beta(V)\eta(X) \\
& + \beta(\xi)ng(V, X) - \beta(\xi)g(X, V) \\
& + \beta(X)\eta(V) - \beta(\xi)g(X, V). \tag{49}
\end{aligned}$$

Now, by using the definition covariant derivative, (8) and (29) we get the following

$$(\nabla_X^* S^*) (V, \xi) = (1 - \lambda) [S(V, \phi X) + \bar{C}(n-1)g(V, \phi X) - \bar{A}g(V, \phi X)]. \tag{50}$$

Taking account of (29), (34), (36), (49) and (50) we get

$$\begin{aligned}
& (1 - \lambda) [S(V, \phi X) + \bar{C}(n-1)g(V, \phi X) - \bar{A}g(V, \phi X)] \\
= & -2(n-1)\bar{C}\alpha(X)\eta(V) + \bar{C}\eta(X)\alpha(V) - \bar{C}\eta(V)\alpha(X) \\
& - (n-1)\bar{C}\alpha(V)\eta(X) + \alpha(\xi)S^*(V, X) \\
& - \bar{C}\eta(V)\alpha(X) + \bar{C}g(X, V)\alpha(\xi) + 2n\beta(X)\eta(V) \\
& - 2\beta(X)\eta(V) + \beta(X)\eta(V) - \eta(X)\beta(V) \\
& + \beta(V)n\eta(X) - \beta(V)\eta(X) \\
& + \beta(\xi)ng(V, X) - \beta(\xi)g(X, V) \\
& + \beta(X)\eta(V) - \beta(\xi)g(X, V). \tag{51}
\end{aligned}$$

Replacing again, X and V by ξ in the foregoing equation and using (29), (6) we obtain

$$[\beta(\xi) - \bar{C}\alpha(\xi)] = 0. \tag{52}$$

Putting V by ξ in (48) and then using (29), (34), (36) and (50) we get

$$\begin{aligned}
 & (1 - \lambda) [S(\phi X, W) + \bar{C}(n - 1)g(\phi X, W) - \bar{A}g(\phi X, W)] \\
 = & -2(n - 1)\bar{C}\alpha(X)\eta(W) - 2\bar{C}\eta(W)\alpha(X) \\
 & + \bar{C}g(X, W)\alpha(\xi) + \alpha(\xi)S^*(X, W) \\
 & - (n - 1)\bar{C}\alpha(W)\eta(X) + \bar{C}\eta(X)\alpha(W) \\
 & + (n - 2)\beta(\xi)g(X, W) + (n - 1)\beta(W)\eta(X) \\
 & - \beta(W)\eta(X) + 2n\beta(X)\eta(W).
 \end{aligned} \tag{53}$$

Setting $X = \xi$ in (53) and using (6), and (36) we obtain

$$\begin{aligned}
 & 0 \\
 = & -3(n - 1)\bar{C}\alpha(\xi)\eta(W) - \bar{C}\eta(W)\alpha(\xi) \\
 & - (n - 1)\bar{C}\alpha(W) + \bar{C}\alpha(W) \\
 & + 3n\beta(\xi)\eta(W) - 2\beta(\xi)\eta(W) \\
 & + (n - 2)\beta(W).
 \end{aligned} \tag{54}$$

Taking $W = \xi$ in (53) and using (6), and (36) we obtain

$$\begin{aligned}
 & 0 \\
 = & -2(n - 1)\bar{C}\alpha(X) - 2\bar{C}\alpha(X) + 2\bar{C}\eta(X)\alpha(\xi) \\
 & - 2(n - 1)\bar{C}\eta(X)\alpha(\xi) + 2(n - 2)\beta(\xi)\eta(X) \\
 & + 2n\beta(X).
 \end{aligned} \tag{55}$$

Replacing W by X in (54)

$$\begin{aligned}
 & 0 \\
 = & -3(n - 1)\bar{C}\alpha(\xi)\eta(X) - \bar{C}\eta(X)\alpha(\xi) \\
 & - (n - 1)\bar{C}\alpha(X) + \bar{C}\alpha(X) \\
 & + 3n\beta(\xi)\eta(X) - 2\beta(\xi)\eta(X) \\
 & + (n - 2)\beta(X).
 \end{aligned} \tag{56}$$

Finally, in view of (52), (54) and (55) we get

$$[\beta(X) - \bar{C}\alpha(X)] = 0. \tag{57}$$

Thus, we can state following

Theorem 2. *There exists no generalised pseudo symmetric Sasakian manifold admitting a general connection, unless $\beta = \bar{C}\alpha$ everywhere, provided $\bar{C} \neq 0$.*

Corollary 1. *There do not exist $[(GPS)_n, \nabla^T]$, $[(GPS)_n, \nabla^s]$, $[(GPS)_n, \nabla^z]$ unless $\beta = 0$, everywhere.*

5 Generalised pseudo Ricci symmetric Sasakian manifold admitting general connection

A non flat n -dimensional Sasakian manifold M^n ($n \geq 3$) is said to be generalised pseudo Ricci symmetric with respect to general connection briefly if the Ricci tensor S^* satisfies the following condition

$$\begin{aligned} & (\nabla_X^* S^*)(U, V) \\ &= 2\alpha^*(X) S^*(U, V) + \alpha^*(U) S^*(X, V) + \alpha^*(V) S^*(U, X) \\ & \quad + 2\beta^*(X) g(U, V) + \beta^*(U) g(X, V) + \beta^*(V) g(U, X). \end{aligned} \quad (58)$$

for all vectors fields $U, V \in \chi(M)$ and where α, β being non zero one forms defined by

$$\alpha^*(X) = g(X, \rho); \beta^*(X) = g(X, \sigma). \quad (59)$$

Replacing V by ξ in (58) and using (36) and (50)

$$\begin{aligned} & (\nabla_X^* S^*)(U, \xi) \\ &= -2(n-1)\bar{C}\alpha^*(X)\eta(U) - (n-1)\bar{C}\alpha^*(U)\eta(X) + \alpha^*(\xi) S^*(U, X) \\ & \quad + 2\beta^*(X)\eta(U) + \beta^*(U)\eta(X) + \beta^*(\xi)g(U, X), \end{aligned} \quad (60)$$

Putting $X = U = \xi$ in foregoing equation and using (36) we get

$$-(n-1)\bar{C}\alpha^*(\xi) + \beta^*(\xi) = 0. \quad (61)$$

By replacing X by ξ in (60) and using (36), (6) we obtain

$$\begin{aligned} & 0 \\ &= -3(n-1)\bar{C}\alpha^*(\xi)\eta(U) - (n-1)\bar{C}\alpha^*(U) \\ & \quad + 3\beta^*(\xi)\eta(U) + \beta^*(U). \end{aligned} \quad (62)$$

Putting $U = \xi$ in (60) and using (36), (6) we get

$$\begin{aligned} & 0 \\ &= -2(n-1)\bar{C}\alpha^*(X) - 2(n-1)\bar{C}\alpha^*(\xi)\eta(X) \\ & \quad + 2\beta^*(X) + 2\beta^*(\xi)\eta(X). \end{aligned} \quad (63)$$

Finally, in view of (61), (62) and (63) we obtain

$$0 = -(n-1)\bar{C}\alpha^*(X) + \beta^*(X). \quad (64)$$

Thus, we can state followings

Theorem 3. *There exists no generalised pseudo ricci symmetric Sasakian manifold admitting a general connection, unless $(n-1)\bar{C}\alpha^* = \beta^*$ everywhere, provided $\bar{C} \neq 0$.*

Corollary 2. *There do not exist $[(GPRS)_n, \nabla^T]$, $[(GPRS)_n, \nabla^s]$ and $[(GPRS)_n, \nabla^z]$ unless $\beta^* = 0$.*

6 Example of a Sasakian manifold with $([(GPS)_n, \nabla^*])$

With the help of [5](See, Ex. 3.1, P.P. 21-22) we introduce an example of 3-dimensional Sasakian manifold spanned by a set of vector fields $\{e_1, e_2, e_3\}$ defined by

$$e_1 = x\left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y}\right) - 2y\frac{\partial}{\partial z}, \quad e_2 = \frac{\partial}{\partial y}, \quad e_3 = \xi = \frac{\partial}{\partial z},$$

where $\{x; y; z\}$ is a standard coordinate in R^3 . Define 1-form η , characteristic vector field ξ , Riemannian metric g and (1-1) tensor ϕ by $\eta(Z) = g(Z, e_3)$, $\xi = \frac{\partial}{\partial z}$, $g(e_i, e_j) = \delta_{ij}$ and $\phi e_1 = -e_2$, $\phi e_2 = e_1$ and $\phi e_3 = 0$. Let ∇ be the Levi-Civita connection with respect to the Riemannian metric g . Then we have $[e_1, e_2] = 2e_3$, $[e_1, e_3] = 0$, $[e_2, e_3] = 0$. Thus, $M(\phi, \xi, \eta, g)$ defines a Sasakian manifold and the Levi-Civita connection ∇ of the metric tensor g can be obtained by using Koszul's formulas which are as follows:

$$\begin{aligned} \nabla_{e_1} e_3 &= -e_2, & \nabla_{e_1} e_2 &= e_3, & \nabla_{e_1} e_1 &= 0, \\ \nabla_{e_2} e_3 &= e_1, & \nabla_{e_2} e_2 &= 0, & \nabla_{e_2} e_1 &= -e_3, \\ \nabla_{e_3} e_3 &= 0, & \nabla_{e_3} e_2 &= e_1, & \nabla_{e_3} e_1 &= -e_2, \end{aligned} \tag{65}$$

$$\begin{aligned} R(e_1, e_2)e_2 &= -3e_1, & R(e_1, e_3)e_3 &= e_1, & R(e_2, e_3)e_3 &= e_2, \\ R(e_1, e_2)e_3 &= 0, & R(e_3, e_2)e_2 &= e_3, & R(e_2, e_1)e_1 &= -3e_2, \\ R(e_1, e_3)e_2 &= 0, & R(e_3, e_1)e_1 &= e_3, & R(e_2, e_1)e_3 &= 0, \end{aligned} \tag{66}$$

and

$$S(e_1, e_1) = -2, S(e_2, e_2) = -2, S(e_3, e_3) = 2. \tag{67}$$

Using (18), (27) (28), (65) and (66) we obtain the following

$$\begin{aligned} \nabla_{e_1}^* e_2 &= e_3 + \lambda e_3, & \nabla_{e_1}^* e_1 &= 0; & \nabla_{e_1}^* e_3 &= -e_2 - \lambda e_2; \\ \nabla_{e_2}^* e_1 &= -e_3 - \lambda e_3; & \nabla_{e_2}^* e_2 &= 0; & \nabla_{e_2}^* e_3 &= e_1 + \lambda e_1; \\ \nabla_{e_3}^* e_1 &= -e_2 - \mu e_2; & \nabla_{e_3}^* e_2 &= e_1 + \mu e_1; & \nabla_{e_3}^* e_3 &= 0, \end{aligned} \tag{68}$$

$$\begin{aligned} R^*(e_1, e_2)e_2 &= -3e_1 - (\lambda^2 - 2\lambda)e_1 + 2\mu e_1, \\ R^*(e_2, e_3)e_3 &= e_2 - (\lambda - \lambda\mu + \mu)e_2, \\ R^*(e_1, e_3)e_3 &= e_1 - (\lambda - \lambda\mu + \mu)e_1 \\ R^*(e_2, e_1)e_1 &= -3e_2 - (\lambda^2 - 2\lambda)e_2 + 2\mu e_2, \\ R^*(e_3, e_2)e_2 &= e_3 - (\lambda - \lambda\mu + \mu)e_3, \\ R^*(e_2, e_1)e_3 &= 0, R^*(e_1, e_2)e_3 = 0, \\ R^*(e_3, e_1)e_1 &= e_3 - (\lambda - \lambda\mu + \mu)e_3, \\ R^*(e_1, e_3)e_2 &= 0, \end{aligned} \tag{69}$$

$$S^*(e_1, e_1) = -2 - \bar{A}, \tag{70}$$

$$S^*(e_2, e_2) = -2 - \bar{A}, \quad (71)$$

$$S^*(e_3, e_3) = -2\bar{C}, \quad (72)$$

and

$$S^*(e_1, e_1) = -2 - \bar{A}, S^*(e_2, e_2) = -2 - \bar{A}, S^*(e_3, e_3) = -2\bar{C}. \quad (73)$$

Using the above results of curvature tensor and (47) and (58) we obtain

$$[\beta(e_i) - \bar{C}\alpha(e_i)] = 0; \forall i = 1, 2, 3; \text{ provided } \bar{C} \neq 0.$$

and

$$-(n-1)\bar{C}\alpha(e_i) + \beta(e_i) = 0, \forall i = 1, 2, 3; \text{ provided } \bar{C} \neq 0.$$

Hence, this example is the necessary condition for the existence of generalized pseudo symmetric and generalized pseudo Ricci-symmetric Sasakian manifolds admitting a general connection, that is, this example supports **Theorem4.1** and **Theorem5.1**.

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