

FINSLERIAN HYPERSURFACES OF A FINSLER SPACE WITH DEFORMED DOUGLAS INFINITE SERIES METRIC

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Abstract

In present paper we studied the geometrical properties of Finslerian hypersurfaces and its reducibility of Cartan C - tensor in various forms for a Finsler space F^n equipped with deformed Infinite series metric. Further we obtained the value of main scalar I for the hypersurface in a two-dimensional case.

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1 Introduction

Matsumoto [7] studied a Finsler metric of two variable α and β on a n -dimensional manifold M^n and summerised all the results for the Finsler space F^n which is equipped with (α, β) -metric. Further in 1998 he [9] introduced a special (α, β) -metric which was defined as

$$L = \alpha + \frac{\beta^2}{\alpha} \quad (1)$$

and named as Douglas type metric and the space equiped with this metric was known as Finsler space with Douglas type metric. Since the Douglas space was a generalization of Berwald space, so this metric was very important in the development of Finsler geometry.

In 2004 Lee and Park [6] introduced a r -th series (α, β) -metric

$$L(\alpha, \beta) = \beta \sum_{k=0}^r \left(\frac{\alpha}{\beta}\right)^k, \quad \alpha < \beta \quad (2)$$

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where α is a Riemannian metric and β is one form. The above equation is reduces in special and important form of an (α, β) -metric for the various values of r . e.g.

1. If $r = 1$ then r -th series metric reduces in a special and important form which is known as Randers metric which is widely used in the field of physics.

2. If $r = 2$ then above metric reduces in $L = \alpha + \beta + \frac{\alpha^2}{\beta}$ which is a combination of Randers metric and Kropina metric.

3. If $r = \infty$ then above metric is expressed as $L(\alpha, \beta) = \frac{\beta^2}{\beta - \alpha}$ which is an remarkable form of an (α, β) that represent the difference of Randers and Matsumoto metric.

Matsumoto introduced the concept of Finslerian hypersurface [8] and studied its geometrical properties in various forms. Further many authors studied hypersurface properties in a Finsler space [1, 2, 3, 4, 5, 10, 11] for various Finsler metrics and obtained very interesting results in the field of Finsler geometry.

In the present paper we combine douglas type Finsler metric $L = \alpha + \frac{\beta^2}{\alpha}$ and Infinite series metric $L = \frac{\beta^2}{\beta - \alpha}$ and introduced a deformed douglas Infinite series metric and studied some intrinsic properties of the hypersurfaces and its reducibility of Cartan C -tensor in various forms for a Finsler space with deformed douglas Infinite series metric. In the last article of present paper we obtain the the value of main scalar I in a two-dimensional case for the hypersurfae of a Finsler space with deformed douglas Infinite series metric.

2 Preliminaries

The concept of Finslerian hypersurfaces introduced by [8] and studied in detail by [4] in a n -dimensional Finsler space $F^n = (M^n, L)$ with respect to cartan connection $C\Gamma = (F_{jk}^i, N_j^i, C_{jk}^i)$ and obtained the expression for fundamental metric tensor g_{ij} and C-tensor C_{ijk} which can be written as

$$g_{ij} = \frac{1}{2} \frac{\partial^2 L^2}{\partial y^i \partial y^j}, \quad C_{ijk} = \frac{1}{2} \frac{\partial g_{ij}}{\partial y^k}, \quad (3)$$

Further Matsumoto [8] and Kitayama [4] considered the parametric form of an hypersurface of an n -dimensional manifold M^n is given by

$$x^i = x^i(u^\alpha)$$

where $u^\alpha \{\alpha = 1, 2, 3, \dots, (n-1)\}$, are the Gaussian coordinates and the hypersurface of M^n is denoted by M^{n-1} .

Again the supporting line element y^i which is tangential to the hypersurface M^{n-1} at the point (u^α) is given by

$$y^i = B_\alpha^i(u)v^\alpha, \quad (4)$$

where the projection factors $B_\alpha^i = \frac{\partial x^i}{\partial u^\alpha}$ represent a tangent space at a point of the hypersurface and matrix corresponding to it is of rank $n - 1$ whereas v^α is the line element of support of the hypersurface M^{n-1} at the point (u^α) .

Since the metric function $L(u, v) = L\{x(u), y(u, v)\}$ satisfied the conditions of a Finsler metric in the hypersurface M^{n-1} , so we have an $(n - 1)$ dimensional Finsler space $F^{n-1} = \{M^{n-1}, L\}$ equipped with the metric $L(u, v)$.

Now the expression for metric tensor, hv-tensor, a unit normal vector, angular metric tensor and the relation between projection factors and its inverse for a Finslerian hypersurface F^{n-1} [8] at a point (u^α) are given by

$$\begin{aligned} g_{\alpha\beta} &= g_{ij}B_\alpha^iB_\beta^j, & C_{\alpha\beta\gamma} &= C_{ijk}B_\alpha^iB_\beta^jB_\gamma^k, \\ g_{ij}\{x(u, v), y(u, v)\}B_\alpha^iN^j &= 0, & g_{ij}\{x(u, v), y(u, v)\}N^iN^j &= 1. \\ h_{\alpha\beta} &= h_{ij}B_\alpha^iB_\beta^j, & h_{ij}B_\alpha^iN^j &= 0, & h_{ij}N^iN^j &= 1. \\ B_i^\alpha &= g^{\alpha\beta}g_{ij}B_\beta^j, & B_\alpha^iB_i^\beta &= \delta_\alpha^\beta, & B_i^\alpha N^i &= 0, & B_\alpha^i N_i &= 0. \\ N_i &= g_{ij}N^j, & B_i^k &= g^{kj}B_{ji}, & B_\alpha^iB_j^\alpha + N^iN_j &= \delta_j^i. \end{aligned} \quad (5)$$

The cartan connection $ICT = (\Gamma_{\beta\gamma}^{*\alpha}, G_\beta^\alpha, C_{\beta\gamma}^\alpha)$ for the Finslerian hypersurface F^{n-1} are given by

$$\begin{aligned} \Gamma_{\beta\gamma}^{*\alpha} &= B_i^\alpha(B_{\beta\gamma}^i + \Gamma_{jk}^{*i}B_\beta^jB_\gamma^k) + M_\beta^\alpha H_\gamma, \\ G_\beta^\alpha &= B_i^\alpha(B_{0\beta}^i + \Gamma_{0j}^{*i}B_\beta^j), & C_{\beta\gamma}^\alpha &= B_i^\alpha C_{jk}^i B_\beta^j B_\gamma^k, \end{aligned}$$

where

$$M_{\beta\gamma} = N_i C_{jk}^i B_\beta^j B_\gamma^k, \quad M_\beta^\alpha = g^{\alpha\gamma} M_{\beta\gamma}, \quad H_\beta = N_i (B_{0\beta}^i + \Gamma_{0j}^{*i} B_\beta^j),$$

and

$$B_{\beta\gamma}^i = \frac{\partial B_\beta^i}{\partial u^\gamma}, \quad B_{0\beta}^i = B_{\alpha\beta}^i v^\alpha.$$

Note: "The tensorial form $M_{\alpha\beta}$ and H_α are known as the second fundamental v-tensor and normal curvature vector respectively".

Further the second fundamental h-tensor $H_{\beta\gamma}$ can be expressed as [8]

$$H_{\beta\gamma} = N_i (B_{\beta\gamma}^i + \Gamma_{jk}^{*i} B_\beta^j B_\gamma^k) + M_\beta H_\gamma, \quad (6)$$

where, $M_\beta = N_i C_{jk}^i B_\beta^j N^k$.

Since from above it is clear that the tensorial quantity $H_{\beta\gamma}$ is not symmetric so we have

$$H_{\beta\gamma} - H_{\gamma\beta} = M_\beta H_\gamma - M_\gamma H_\beta. \quad (7)$$

Now the h and v-covariant derivatives of the projection factor B_α^i with respect to ICT can be expressed as

$$B_{\alpha|\beta}^i = H_{\alpha\beta} N^i, \quad B_\alpha^i|_\beta = M_{\alpha\beta} N^i.$$

Now when we contracting $H_{\beta\gamma}$ and $H_{\gamma\beta}$ by v^β we get

$$H_{0\gamma} = H_\gamma, \quad H_{\gamma 0} = H_\gamma + M_\gamma H_0, \quad (8)$$

Thus following important results for the Finslerian hypersurface [8] we shall use in our present paper

Lemma 1. *The normal curvature tensor vanishes identically iff the normal curvature vector vanishes in a Finslerian hypersurface $F^{(n-1)}$.*

Lemma 2. *If F^n be a Finsler space and $F^{(n-1)}$ be its hypersurface then the hypersurface $F^{(n-1)}$ will be a hyperplane of the first kind iff normal curvature vector vanishes identically.*

Lemma 3. *If F^n be a Finsler space and $F^{(n-1)}$ be its hypersurface then the hypersurface $F^{(n-1)}$ will be a hyperplane of the second kind iff normal curvature vector and second fundamental h-tensor vanishes identically.*

Lemma 4. *If F^n be a Finsler space and $F^{(n-1)}$ be its hypersurface then the hypersurface $F^{(n-1)}$ will be a hyperplane of the third kind iff normal curvature vector, second fundamental h and v tensor vanishes identically.*

3 Finsler space with deformed Douglas infinite series metric

The deformed Douglas Infinite series metric is a combination of Matsumoto Douglas type and Infinite series metric which we defined as

Definition 1. *Let F^n be an n -dimensional Finsler space consisting of an n -dimensional differentiable manifold M^n equipped with a fundamental function L defined as*

$$L(\alpha, \beta) = \alpha + \frac{\beta^2}{\alpha} + \frac{\beta^2}{(\beta - \alpha)} \quad (9)$$

then the metric L is known as deformed Infinite series and the Finsler space $F^n = \{M^n, L(\alpha, \beta)\}$ equipped with this metric is known as deformed infinite series Finsler space.

Now differentiating equation (9) partially with respect to α and β we have following important identities

$$L_\alpha = \frac{\alpha^4 - \beta^4 - 2\alpha^3\beta - 2\alpha\beta^3 + \alpha^2\beta^2}{\alpha^2(\beta - \alpha)^2}, \quad L_\beta = \frac{2\beta^3 - 3\alpha\beta^2}{\alpha(\beta - \alpha)^2} \quad L_{\alpha\alpha} = \frac{2\{\alpha^3 + (\beta - \alpha)^3\}\beta^2}{\alpha^3(\beta - \alpha)^2}$$

$$L_{\beta\beta} = \frac{2\{\alpha^3 + (\beta - \alpha)^3\}}{\alpha(\beta - \alpha)^3}, \quad L_{\alpha\beta} = \frac{-2\beta\{\alpha^3 + (\beta - \alpha)^3\}\beta}{\alpha^2(\beta - \alpha)^3}$$

where $L_\alpha = \frac{\partial L}{\partial \alpha}$, $L_\beta = \frac{\partial L}{\partial \beta}$, $L_{\alpha\alpha} = \frac{\partial L_\alpha}{\partial \alpha}$, $L_{\beta\beta} = \frac{\partial L_\beta}{\partial \beta}$, $L_{\alpha\beta} = \frac{\partial L_\alpha}{\partial \beta}$.

In Finsler space $F^n = \{M^n, L(\alpha, \beta)\}$ the normalized element of support $l_i = \partial_i L$ and angular metric tensor h_{ij} are given by:

$$l_i = \alpha^{-1}L_\alpha Y_i + L_\beta b_i \tag{10}$$

$$h_{ij} = pa_{ij} + q_0 b_i b_j + q_{-1}(b_i Y_j + b_j Y_i) + q_{-2} Y_i Y_j \tag{11}$$

where $Y_i = a_{ij} y^j$ and the scalars p, q_0, q_{-1} and q_{-2} are constants and its values are given below

$$p = \frac{(\beta^3 - \alpha^3 + \alpha^2\beta)(\alpha^4 - \beta^4 - 2\alpha\beta^3 - 2\alpha^3\beta + \alpha^2\beta^2)}{\alpha^4(\beta - \alpha)^3}, \tag{12}$$

$$q_0 = \frac{2(\beta^3 - \alpha^3 + \alpha^2\beta)\{\alpha^3 + (\beta - \alpha)^3\}}{\alpha^2(\beta - \alpha)^4},$$

$$q_{-1} = \frac{-2\beta(\beta^3 - \alpha^3 + \alpha^2\beta)\{\alpha^3 + (\beta - \alpha)^3\}}{\alpha^4(\beta - \alpha)^4},$$

$$q_{-2} = \frac{(\beta^3 - \alpha^3 + \alpha^2\beta)(\alpha^5 + 3\beta^5 + 3\alpha^3\beta^2 + 7\alpha^2\beta^3 - 9\alpha\beta^4)}{\alpha^6(\beta - \alpha)^4}.$$

Note: 0, -1, -2 in the subscript represents homogeneity of the respective terms.

Fundamental metric tensor $g_{ij} = \frac{1}{2}\partial_i \partial_j L^2$ and its reciprocal tensor g^{ij} for $L = L(\alpha, \beta)$ are given by [8]

$$g_{ij} = pa_{ij} + p_0 b_i b_j + p_{-1}(b_i Y_j + b_j Y_i) + p_{-2} Y_i Y_j \tag{13}$$

$$g^{ij} = p^{-1} a^{ij} - s_0 b^i b^j - s_{-1}(b^i y^j + b^j y^i) - s_{-2} y^i y^j \tag{14}$$

where $b^i = a^{ij} b_j$ and $b^2 = a_{ij} b^i b^j$

$$p_0 = q_0 + L_\beta^2, \quad p_{-1} = q_{-1} + L^{-1} p L_\beta, \quad p_{-2} = q_{-2} + p^2 L^{-2} \tag{15}$$

$$s_0 = \frac{1}{\tau p} \{pp_0 + (p_0 p_{-2} - p_{-1}^2)\alpha^2\}, \tag{16}$$

$$s_{-1} = \frac{1}{\tau p} \{pp_{-1} + (p_0 p_{-2} - p_{-1}^2)\beta\},$$

$$s_{-2} = \frac{1}{\tau p} \{pp_{-2} + (p_0 p_{-2} - p_{-1}^2)b^2\},$$

$$\tau = p(p + p_0 b^2 + p_{-1}\beta) + (p_0 p_{-2} - p_{-1}^2)(\alpha^2 b^2 - \beta^2)$$

The hv-torsion tensor $C_{ijk} = \frac{1}{2}\dot{\partial}_k g_{ij}$ is given by

$$2pC_{ijk} = p_{-1}(h_{ij}m_k + h_{jk}m_i + h_{ki}m_j) + \gamma_1 m_i m_j m_k \quad (17)$$

where,

$$\gamma_1 = p \frac{\partial p_0}{\partial \beta} - 3p_{-1}q_0, \quad m_i = b_i - \alpha^{-2}\beta Y_i \quad (18)$$

Here m_i is a non-vanishing covariant vector orthogonal to the element of support y^i . Thus we have

Proposition 1. *The normalised supporting element l_i and angular metric tensor h_{ij} of an n -dimensional Finsler space F^n equipped with a deformed Douglas Infinite series metric L are given by (10) and (11) respectively.*

Proposition 2. *The fundamental metric tensor g_{ij} and its reciprocal tensor g^{ij} of an n -dimensional Finsler space F^n equipped with a deformed Douglas Infinite series metric L are given by (13) and (14) respectively.*

Proposition 3. *The Cartan hv-torsion tensor of an n -dimensional Finsler space F^n equipped with a deformed Douglas Infinite series metric L is given by (17).*

Let $\{\overset{i}{j}k\}$ be the component of christoffel symbols of the associated Riemannian space R^n and ∇_k be the covariant derivative with respect to x^k relative to this christoffel symbol. Now we define,

$$2E_{ij} = b_{ij} + b_{ji}, \quad 2F_{ij} = b_{ij} - b_{ji} \quad (19)$$

where $b_{ij} = \nabla_j b_i$.

Let $CT = (\Gamma_{jk}^{*i}, \Gamma_{0k}^{*i}, \Gamma_{jk}^i)$ be the cartan connection of F^n . The difference tensor $D_{jk}^i = \Gamma_{jk}^{*i} - \{\overset{i}{j}k\}$ of the special Finsler space F^n is given by

$$\begin{aligned} D_{jk}^i &= B^i E_{jk} + F_k^i B_j + F_j^i B_k + B_j^i b_{0k} + B_k^i b_{0j} - b_{0m} g^{im} B_{jk} \\ &\quad - C_{jm}^i A_k^m - C_{km}^i A_j^m + C_{jkm} A_s^m g^{is} + \lambda^s (C_{jm}^i C_{sk}^m + \\ &\quad C_{km}^i C_{sj}^m - C_{jk}^m C_{ms}^i) \end{aligned} \quad (20)$$

where

$$\begin{aligned} B_k &= p_0 b_k + p_{-1} Y_k, \quad B^i = g^{ij} B_j, \quad F_i^k = g^{kj} F_{ji} \\ B_{ij} &= \frac{\{p_{-1}(a_{ij} - \alpha^{-2} Y_i Y_j) + \frac{\partial p_0}{\partial \beta} m_i m_j\}}{2}, \quad B_i^k = g^{kj} B_{ji} \\ A_k^m &= B_k^m E_{00} + B^m E_{k0} + B_k F_0^m + B_0 F_k^m \\ \lambda^m &= B^m E_{00} + 2B_0 F_0^m, \quad B_0 = B_i y^i \end{aligned} \quad (21)$$

where $'0'$ denote contraction with y^i except for the quantities p_0, q_0 and s_0 . Thus

Proposition 4. *The difference tensor D_{jk}^i of the Cartan connection CT for the n -dimensional Finsler space F^n equipped with a deformed Douglas Infinite series metric L is given by (20).*

4 Finslerian hypersurface $F^{(n-1)}(c)$ for a Finsler space with deformed Douglas infinite series metric

Let us consider a Finsler space with the deformed Infinite series metric $L(\alpha, \beta) = \alpha + \frac{\beta^2}{\alpha} + \frac{\beta^2}{(\beta-\alpha)}$, where, $\alpha^2 = a_{ij}(x)y^i y^j$ is a Riemannian metric and vector field $b_i(x) = \frac{\partial b}{\partial x^i}$ is a gradient of some scalar function $b(x)$. Now we consider a hypersurface $F^{(n-1)}(c)$ given by equation $b(x) = c$, a constant [11].

From the parametric equation $x^i = x^i(u^\alpha)$ of $F^{n-1}(c)$, we get

$$\frac{\partial b(x)}{\partial u^\alpha} = 0 \quad \frac{\partial b(x)}{\partial x^i} \frac{\partial x^i}{\partial u^\alpha} = 0, \quad b_i B_\alpha^i = 0$$

Above shows that $b_i(x)$ are covariant component of a normal vector field of hypersurface $F^{n-1}(c)$. Further, we have

$$b_i B_\alpha^i = 0 \quad \text{and} \quad b_i y^i = 0 \quad \text{i.e} \quad \beta = 0 \tag{22}$$

and induced metric $L(u, v)$ of $F^{n-1}(c)$ is given by

$$L(u, v) = a_{\alpha\beta} v^\alpha v^\beta, a_{\alpha\beta} = a_{ij} B_\alpha^i B_\beta^j \tag{23}$$

which is a Riemannian metric.

Writing $\beta = 0$ in the equations (10), (11) and (13) we get

$$\begin{aligned} p = 1, \quad q_0 = 0, \quad q_{-1} = 0 \quad q_{-2} = -\alpha^{-2} \quad p_0 = 0 \quad p_{-1} = 0 \\ p_{-2} = 0 \quad \tau = 1, \quad s_0 = 0 \quad s_{-1} = 0 \quad s_{-2} = 0 \end{aligned} \tag{24}$$

from (12) we get,

$$g^{ij} = a^{ij} \tag{25}$$

thus along $F^{n-1}(c)$, (25) and (22) leads to

$$g^{ij} b_i b_j = b^2$$

So we get

$$b_i(x(u)) = b N_i, \quad b^2 = a^{ij} b_i b_j \tag{26}$$

where b is the length of the vector b^i

Again from (25) and (26), we get

$$b^i = a^{ij} b_j = N^i \tag{27}$$

thus we have,

Proposition 5. *The induced Riemannian metric in a Finslerian hypersurface $F^{(n-1)}(c)$ of the Finsler space F^n equipped with a deformed Douglas Infinite series metric is given by (23) and its scalar function $b(x)$ is given by (26) and (27).*

Now the angular metric tensor h_{ij} and metric tensor g_{ij} of F^n are given by

$$h_{ij} = a_{ij} - \frac{1}{\alpha^2} Y_i Y_j \quad \text{and} \quad g_{ij} = a_{ij} \quad (28)$$

From equation (22), (28) and (5) it follows that if $h_{\alpha\beta}^{(a)}$ denote the angular metric tensor of the Riemannian $a_{ij}(x)$ then we have along $F_{(c)}^{n-1}$, $h_{\alpha\beta} = h_{\alpha\beta}^{(a)}$.

$$\text{thus along } F_{(c)}^{n-1}, \quad \frac{\partial p_0}{\partial \beta} = \frac{-6}{\alpha}$$

from equation (16) we get

$$r_1 = \frac{-6}{\alpha}, \quad m_i = b_i$$

then hv-torsion tensor becomes

$$C_{ijk} = -\frac{3}{\alpha} b_i b_j b_k \quad (29)$$

in the deformed Douglas Infinite series Finsler hypersurface $F_{(c)}^{(n-1)}$. Due to fact from (5), (6), (8), (22) and (29) we have

$$M_{\alpha\beta} = 0 \quad \text{and} \quad M_\alpha = 0 \quad (30)$$

Therefore from equation (6) it follows that $H_{\alpha\beta}$ is symmetric. Thus we have

Proposition 6. *The second fundamental v-tensor in a Finslerian hypersurface $F_{(c)}^{(n-1)}$ of the Finsler space F^n equipped with a deformed Douglas Infinite series metric is given by (30) and the second fundamental h-tensor $H_{\alpha\beta}$ is symmetric.*

Now from (22) we have $b_i B_\alpha^i = 0$. Then we have

$$b_{i|\beta} B_\alpha^i + b_i B_{\alpha|\beta}^i = 0$$

Therefore, from (8) and using $b_{i|\beta} = b_{i|j} B_\beta^j + b_i |j N^j H_\beta$, we have

$$b_{i|j} B_\alpha^i B_\beta^j + b_{i|j} B_\alpha^i N^j H_\beta + b_i H_{\alpha\beta} N^i = 0 \quad (31)$$

since $b_i |j = -b_h C_{ij}^h$, we get

$$b_{i|j} B_\alpha^i N^j = 0$$

Therefore from equation (31) we have,

$$b H_{\alpha\beta} + b_{i|j} B_\alpha^i B_\beta^j = 0 \quad (32)$$

because $b_{i|j}$ is symmetric. Now contracting (32) with v^β and using (4) we get

$$b H_\alpha + b_{i|j} B_\alpha^i y^j = 0 \quad (33)$$

Again contracting by v^α equation (33) and using (4), we have

$$bH_0 + b_{i|j}y^i y^j = 0 \tag{34}$$

Now by using Lemmas 1, 2 and equation (34), it is clear that hypersurface $F_{(c)}^{(n-1)}$ of Finsler space with deformed Douglas Infinite series is a hyperplane of first kind if and only if $H_0 = 0$.

Since $b_{i|j}$ represent the covariant derivative with respect to CT in the Finsler space F^n defined on y^i , but $b_{ij} = \nabla_j b_i$ is the covariant derivative with respect to Riemannian connection $\{^i_{jk}\}$. Hence b_{ij} does not depend on y^i . So we shall consider the difference $b_{i|j} - b_{ij}$ where $b_{ij} = \nabla_j b_i$. Since b_i is a gradient vector, then from (19) we have

$$E_{ij} = b_{ij} \quad F_{ij} = 0 \quad \text{and} \quad F_j^i = 0$$

Thus using above fact the in equation (20), the difference tensor can be rewritten as

$$\begin{aligned} D_{jk}^i &= B^i b_{jk} + B_j^i b_{0k} + B_k^i b_{0j} - b_{0m} g^{im} B_{jk} - C_{jm}^i A_k^m - C_{km}^i A_j^m \\ &\quad + C_{jkm} A_s^m g^{is} + \lambda^s (C_{jm}^i C_{sk}^m + C_{km}^i C_{sj}^m - C_{jk}^m C_{ms}^i) \end{aligned} \tag{35}$$

where

$$\begin{aligned} B_i &= 0, \quad B^i = 0, \quad B_i B^i = 0, \quad \lambda^m = B^m b_{00}, \quad B_{ij} = -\frac{3}{\alpha} b_i b_j, \\ B_j^i &= -\frac{3}{\alpha} b^2, \quad A_k^m = B_k^m b_{00} + B^m b_{k0} \end{aligned} \tag{36}$$

In view of (24) and (25), the relation in (19) becomes to by virtue of (36) we have $B_0^i = 0$, $B_{i0} = 0$ which leads $A_0^m = B^m b_{00}$.

Now contracting (35) by y^k we get

$$D_{j0}^i = B^i b_{j0} + B_j^i b_{00} - B^m C_{jm}^i b_{00}$$

Again contracting the above equation with respect to y^j we have

$$D_{00}^i = 0$$

Paying attention to (22), along $F_{(c)}^{(n-1)}$, we get

$$b_i D_{j0}^i = -\frac{3}{\alpha} b^2 b_i b_{00} \tag{37}$$

Now we contract (37) by y^j we have

$$b_i D_{00}^i = 0 \tag{38}$$

From (26), (27), (30) and $M_\alpha = 0$, we have

$$b_i b^m C_{jm}^i B_\alpha^j = b^2 M_\alpha = 0$$

Thus the relation $b_{i|j} = b_{ij} - b_r D_{ij}^r$ the equation (37) and (38) gives

$$b_{i|j} y^i y^j = b_{00} - b_r D_{00}^r = b_{00}$$

Consequently (33) and (34) may be written as

$$bH_\alpha + b_{i0} B_\alpha^i = 0, \quad \text{and} \quad bH_0 + b_{00} = 0 \quad (39)$$

Thus the condition $H_0 = 0$ is equivalent to $b_{00} = 0$. Using the fact $\beta = b_i y^i = 0$ the condition $b_{00} = 0$ can be written as $b_{ij} y^i y^j = b_i y^i b_j y^j$ for some $c_j(x)$. Thus we can write,

$$2b_{ij} = b_i c_j + b_j c_i \quad (40)$$

Now from (22) and (40) we get

$$b_{00} = 0, \quad b_{ij} B_\alpha^i B_\beta^j = 0, \quad b_{ij} B_\alpha^i y^j = 0$$

Hence using the above condition and equation (39) we have

$$H_\alpha = 0 \quad (41)$$

Thus using Lemma 2 and above condition we have

Theorem 1. *The necessary and sufficient condition for a Finslerian hypersurface $F^{(n-1)}(c)$ of the Finsler space F^n equipped with a deformed Douglas Infinite series metric to be a hyperplane of first kind is (40).*

again from (40) and (36) we get

$$b_{i0} b^i = \frac{c_0 b^2}{2}, \quad \lambda^m = 0, \quad A_j^i B_\beta^j = 0 \quad \text{and} \quad B_{ij} B_\alpha^i B_\beta^j = -\frac{3}{\alpha} b_i b_j B_\alpha^i B_\beta^j = 0.$$

Now we use equation (25), (26), (27), (30) and (35) then we have

$$b_r D_{ij}^r B_\alpha^i B_\beta^j = 0 \quad (42)$$

Thus the equation (32) reduces to

$$H_{\alpha\beta} = 0 \quad (43)$$

Hence the hypersurface $F_{(c)}^{n-1}$ is umbilic.

Now from Lemma 3, $F_{(c)}^{(n-1)}$ is a hyperplane of second kind if and only if $H_\alpha = 0$ and $H_{\alpha\beta} = 0$. Thus from (42), we get

$$c_0 = c_i(x) y^i = 0$$

Therefore there exist a function $\psi(x)$ such that

$$c_i(x) = \psi(x) b_i(x)$$

Therefore (40) we get

$$2b_{ij} = b_i(x)\psi(x)b_j(x) + b_j(x)\psi(x)b_i(x)$$

This can also be written as

$$b_{ij} = \psi(x)b_ib_j \tag{44}$$

Thus using the condition (41) and (43) we have

Theorem 2. *The necessary and sufficient condition for in a Finslerian hypersurface $F^{(n-1)}(c)$ of the Finsler space F^n equipped with a deformed Douglas Infinite series metric to be a hyperplane of second kind is (44).*

Again Lemma 4, together with (30) and $M_\alpha = 0$ shows that $F_{(c)}^{n-1}$ become a hyperplane of third kind.

Theorem 3. *The Finslerian hypersurface $F^{(n-1)}(c)$ of the Finsler space F^n equipped with a deformed Douglas Infinite series metric is a hyperplane of the third kind.*

5 Some important result of hypersurface $F^{(n-1)}(c)$ of a Finsler space $F^n(c)$ with deformed Douglas infinite series metric

The hv-torsion tensor C_{ijk} of $F^{(n-1)}(c)$ with deformed infinite series metric written in equation (29) as

$$C_{ijk} = \frac{-3}{\alpha}b_ib_jb_k$$

Contracting by g^{jk} , we have

$$C_i = C_{ijk}g^{jk} = \frac{-3b^2}{\alpha}b_i$$

This implies that

$$b_i = \frac{-\alpha}{3b^2}C_i$$

Therefore equation (29) becomes

$$C_{ijk} = \frac{\alpha^2}{9b^6}C_iC_jC_k \tag{45}$$

Definition 2. *A Finsler space F^n is called C2-like,if the (h) hv-tortion tensor C_{ijk} is written in the form*

$$C_{ijk} = \frac{1}{C^2}C_iC_jC_k$$

Thus using the above ddefinition and equation (45) we have

$$C = \frac{3b^3}{\alpha} \tag{46}$$

Thus

Proposition 7. *The Finslerian hypersurface $F^{(n-1)}(c)$ of the Finsler space F^n equipped with a deformed Douglas Infinite series metric is always be a C2-like Finsler space if equation (46) is satisfied.*

Since the main scalar of two dimensional Finsler space is defined as

$$LC_{ijk} = Im_i m_j m_k$$

From equation (16) $m_i = b_i$ we have

$$LC_{ijk} = Ib_i b_j b_k$$

Contracting g^{jk} we have

$$LC_i = Ib^2 b_i$$

which gives

$$b_i = \frac{L}{b^2} C_i$$

Now the main scalar of two dimensional Finsler

$$LC_{ijk} = \frac{IL^3}{b^6} C_i C_j C_k \quad (47)$$

From equation (45) and (47), we have

$$I = \frac{\alpha^2}{9L^2} \quad (48)$$

Proposition 8. *The main scalar I of a Finslerian hypersurface $F^{(n-1)}(c)$ for the Finsler space F^n equipped with a deformed Douglas Infinite series metric in a two dimensional case is given by (48).*

6 Conclusion

In the present paper, we obtained the conditions for a Finslerian hypersurface $F^{(n-1)}(c)$ of a Finsler space F^n with deformed Douglas Infinite series metric to be a hyperplane of first, second, and third kind in the Theorems 1, 2, and 3, respectively. Further for application point of view we also obtained the Proposition 7 which states the condition under which hypersurface $F^{n-1}(c)$ will be reduces in C2-like Finsler space and in Propostion 8 gives the value of the main scalar I for the hypersurface in two-dimensional case.

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